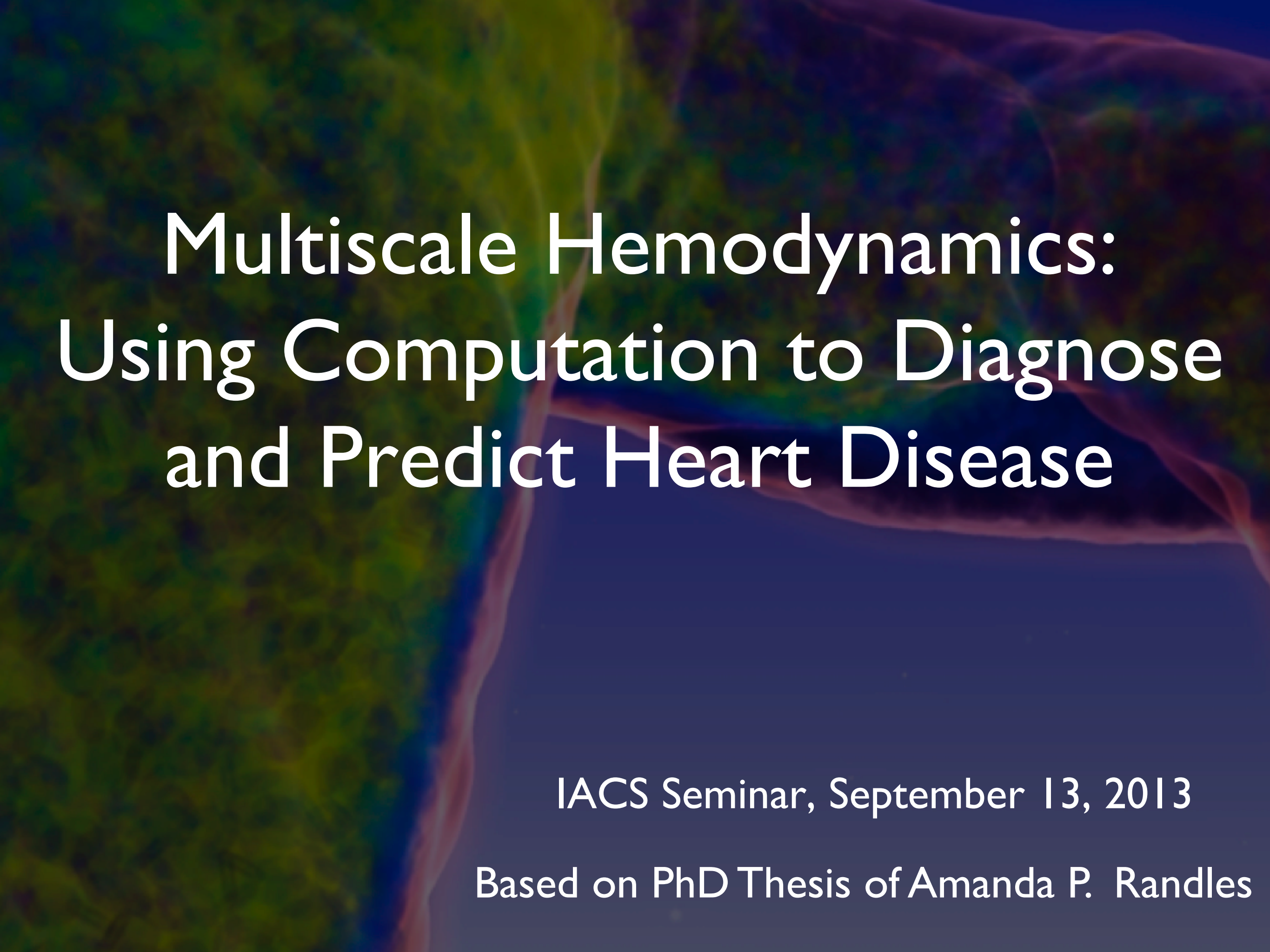




Multiscale Hemodynamics: Using Computation to Diagnose and Predict Heart Disease

IACS Seminar, September 13, 2013

Based on PhD Thesis of Amanda P. Randles

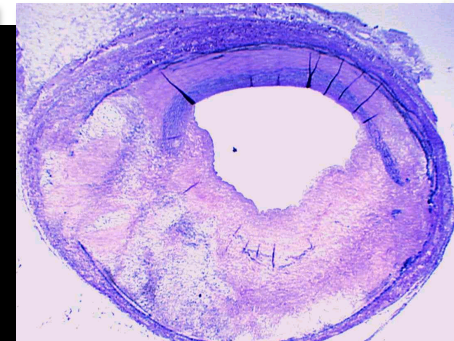
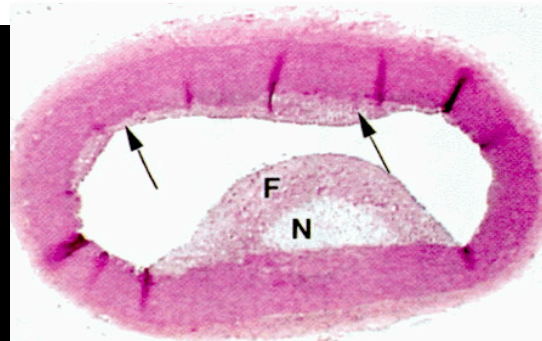
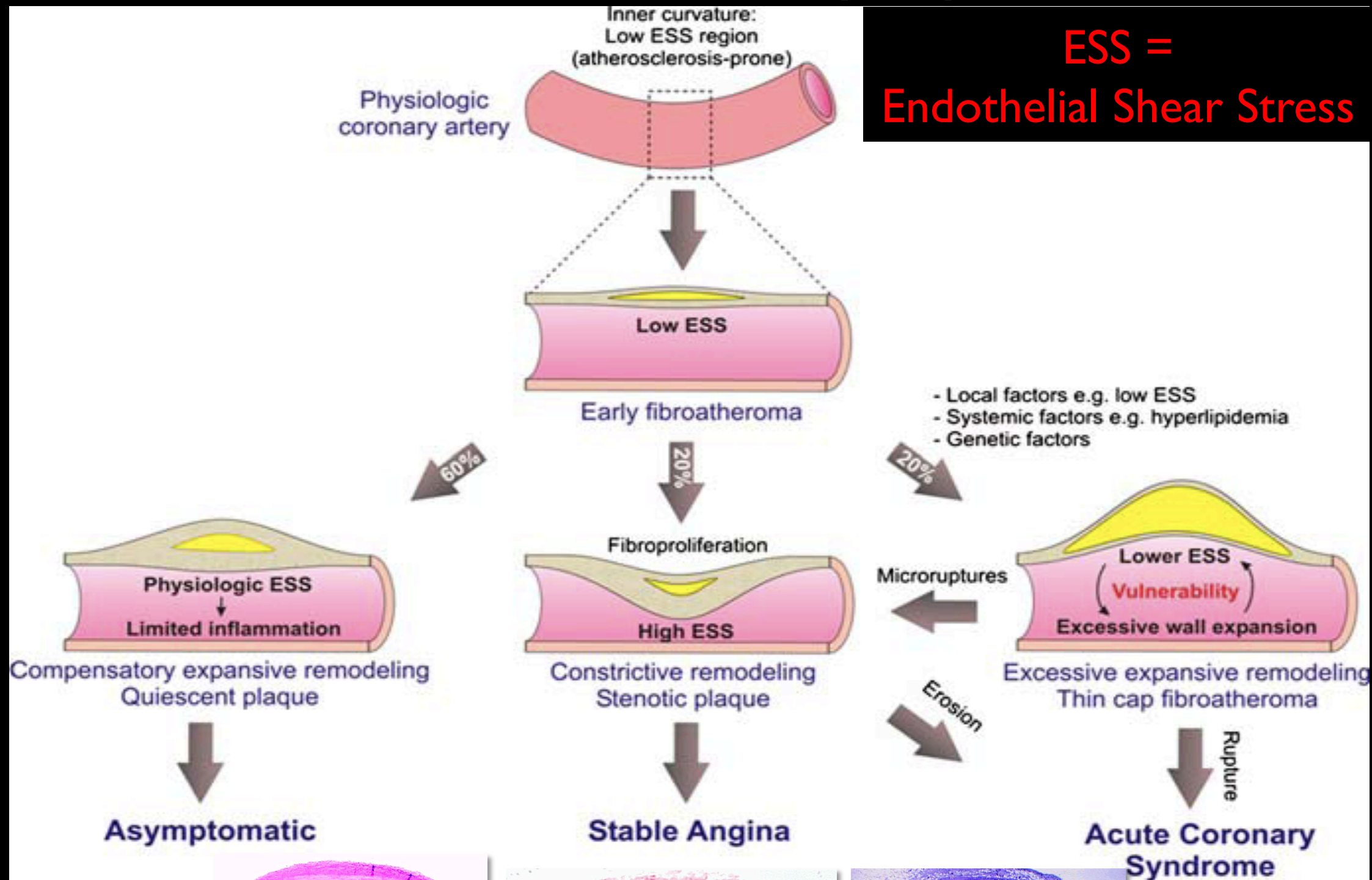
Cardiovascular Disease

- Leading cause of death in the western world
- 1 in ~3 deaths in the US alone
- 50% of instances occur without prior symptoms



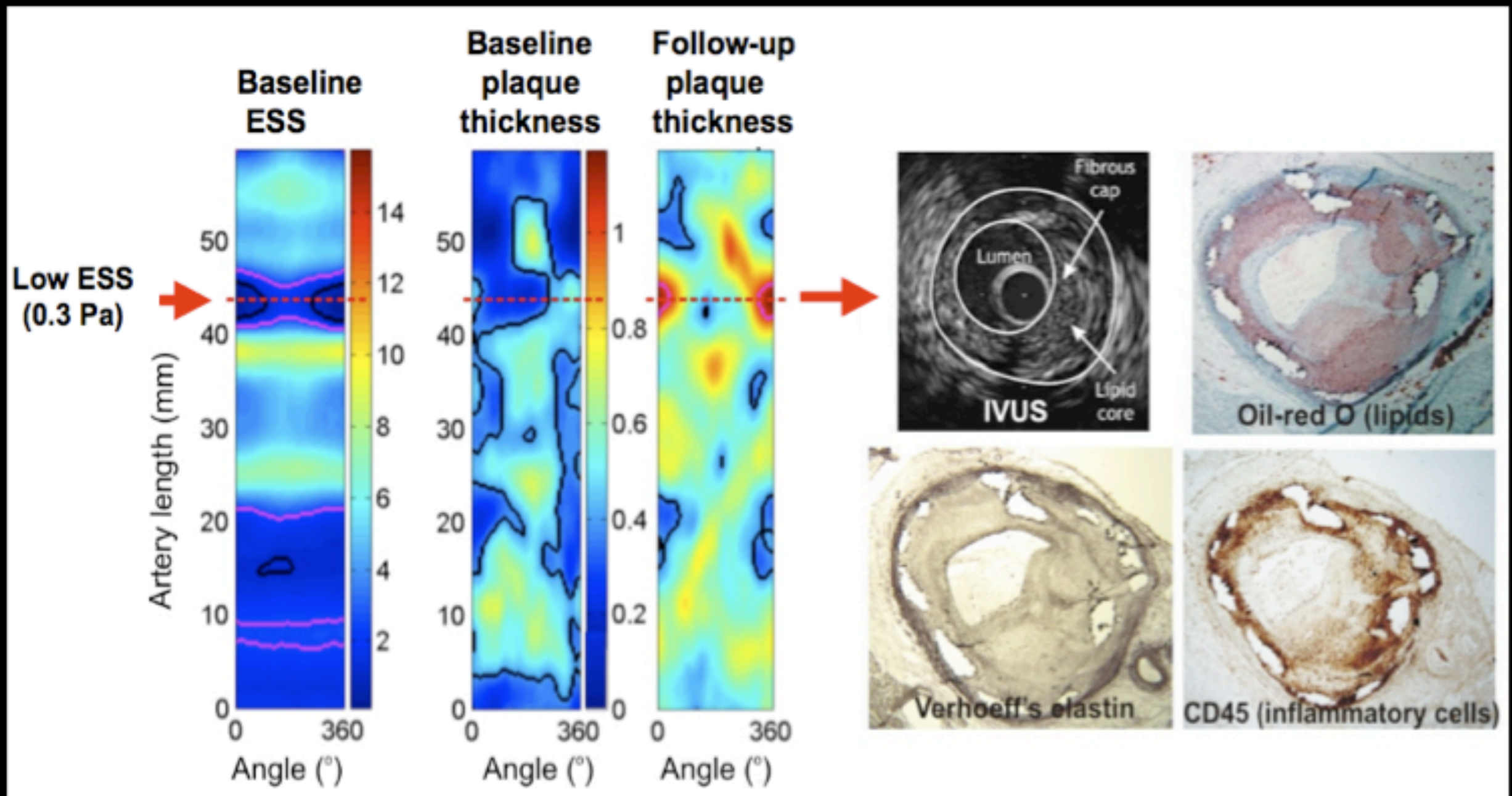
Formation and evolution of plaques

**ESS =
Endothelial Shear Stress**



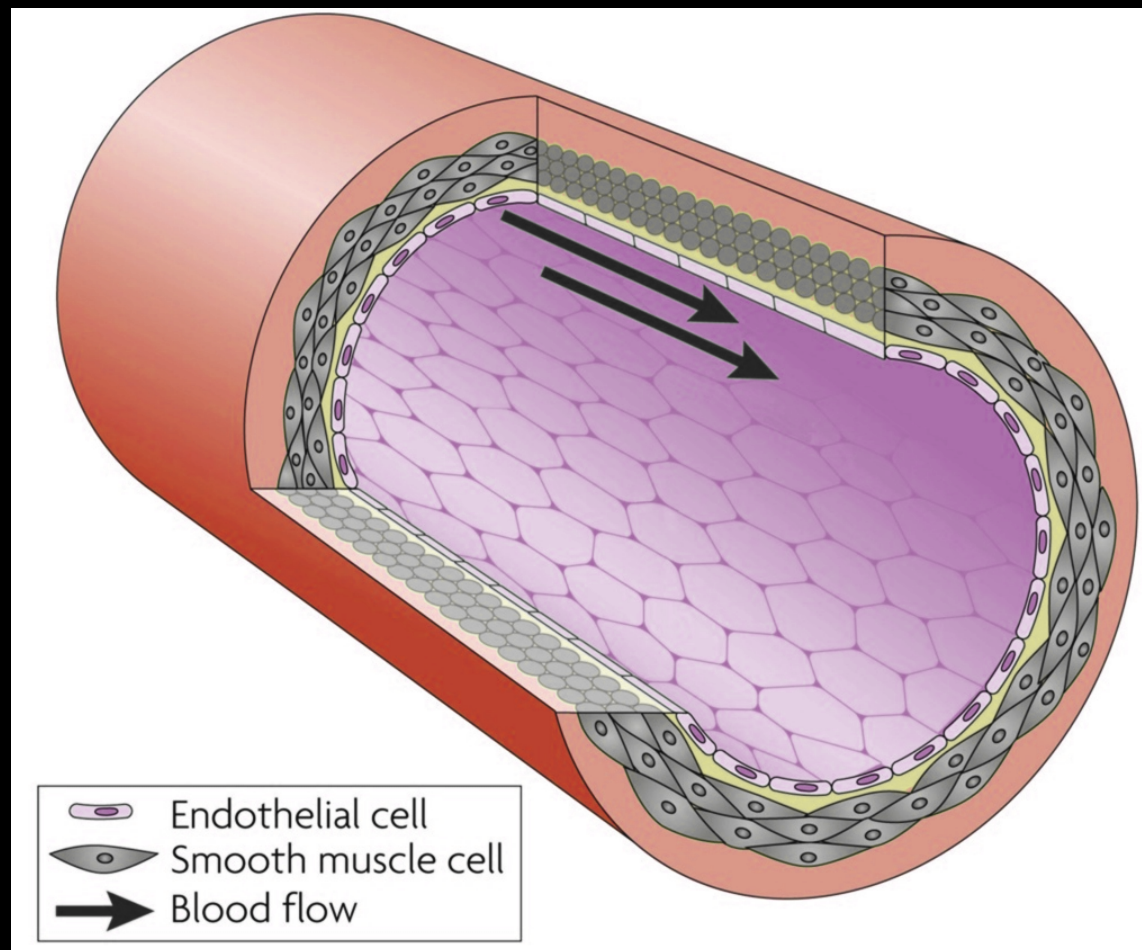
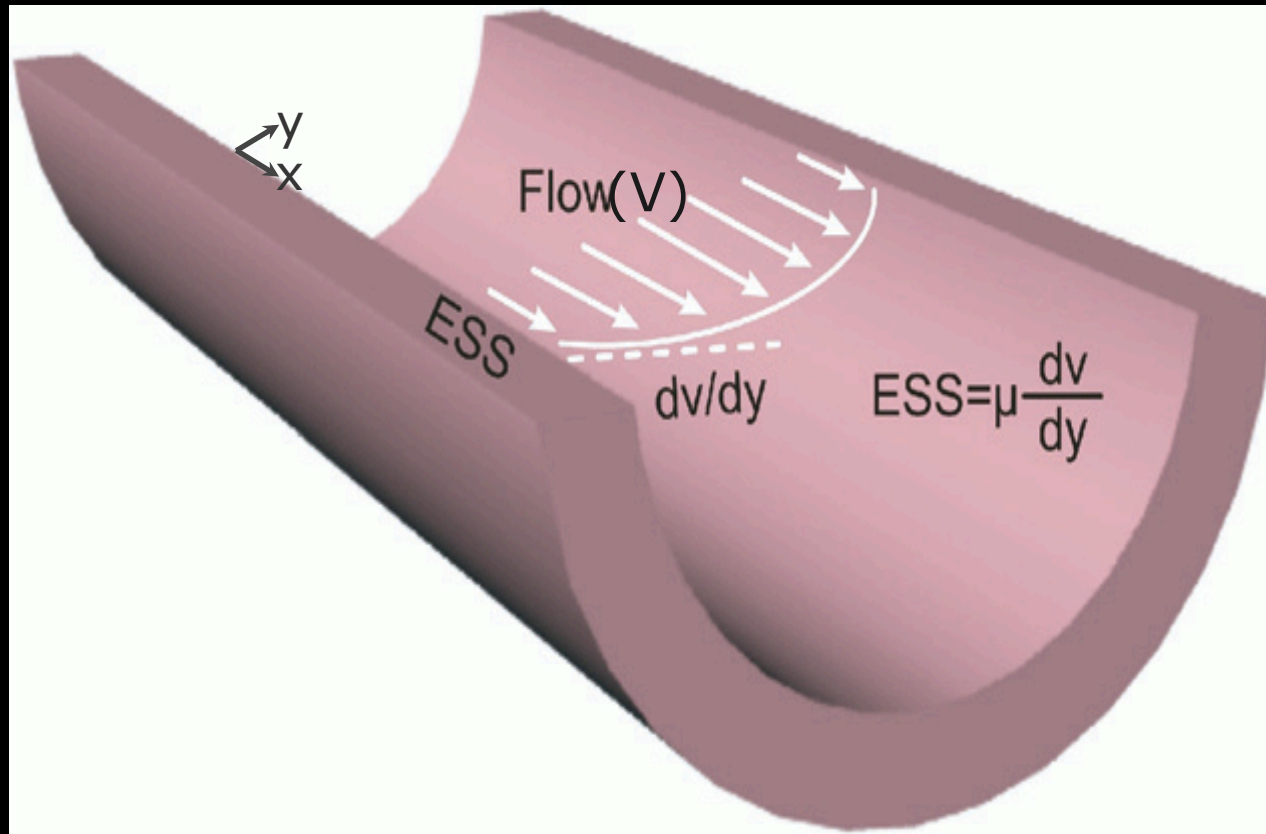
Vascular Remodeling

Role of Endothelial Shear Stress (ESS)

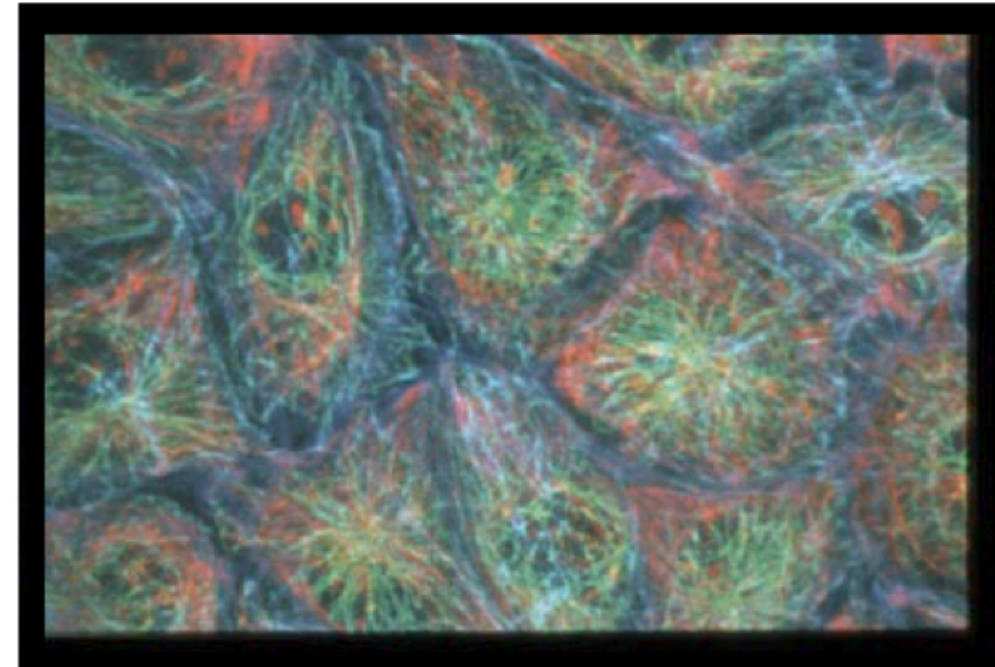


Currently, the only way to assess a patient's endothelial shear stress is through simulation

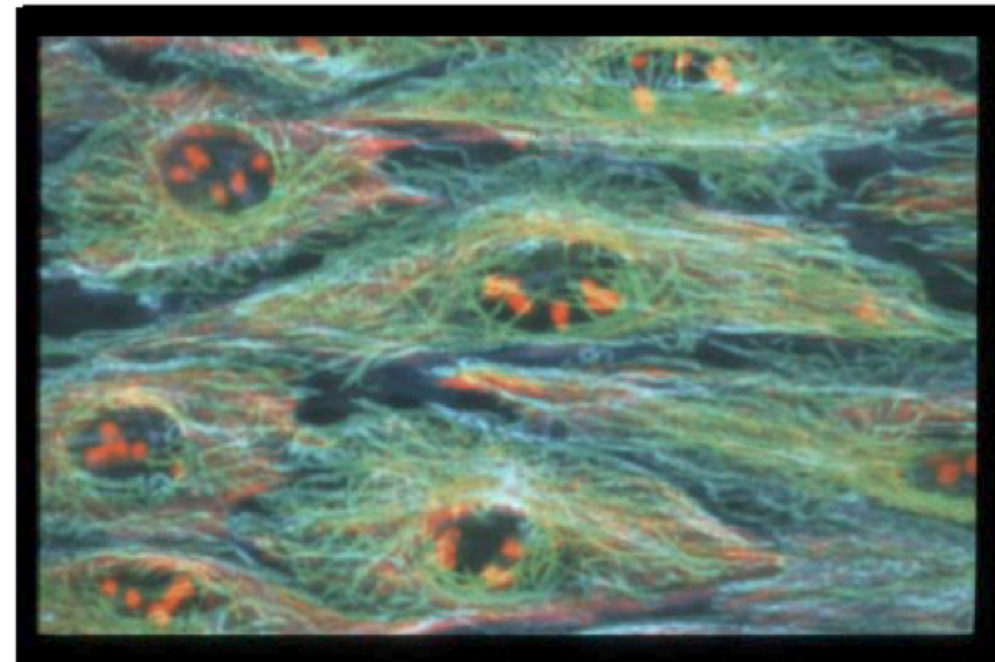
How does the flow reshape the endothelium?



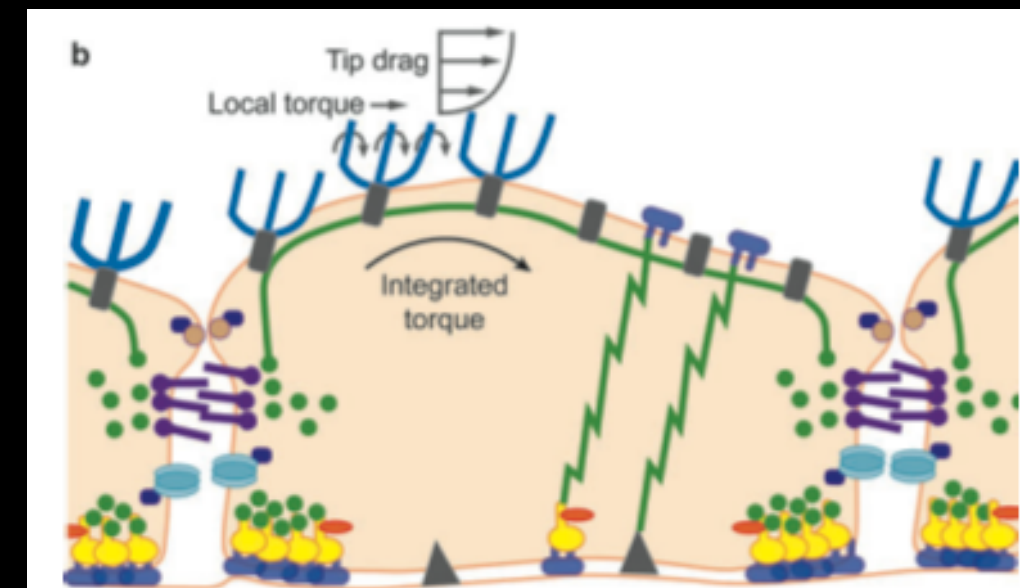
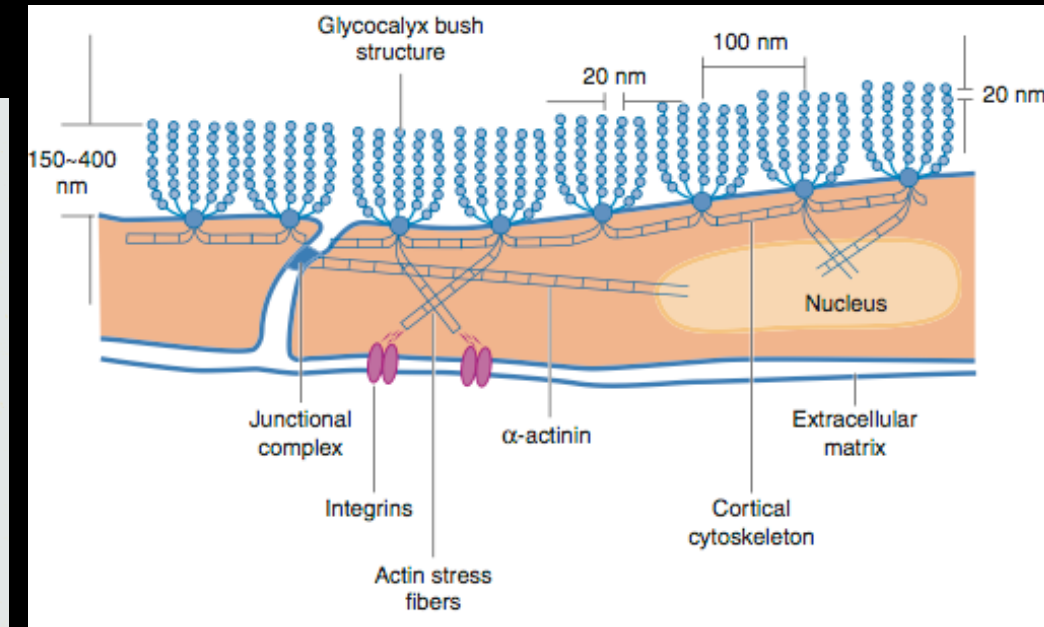
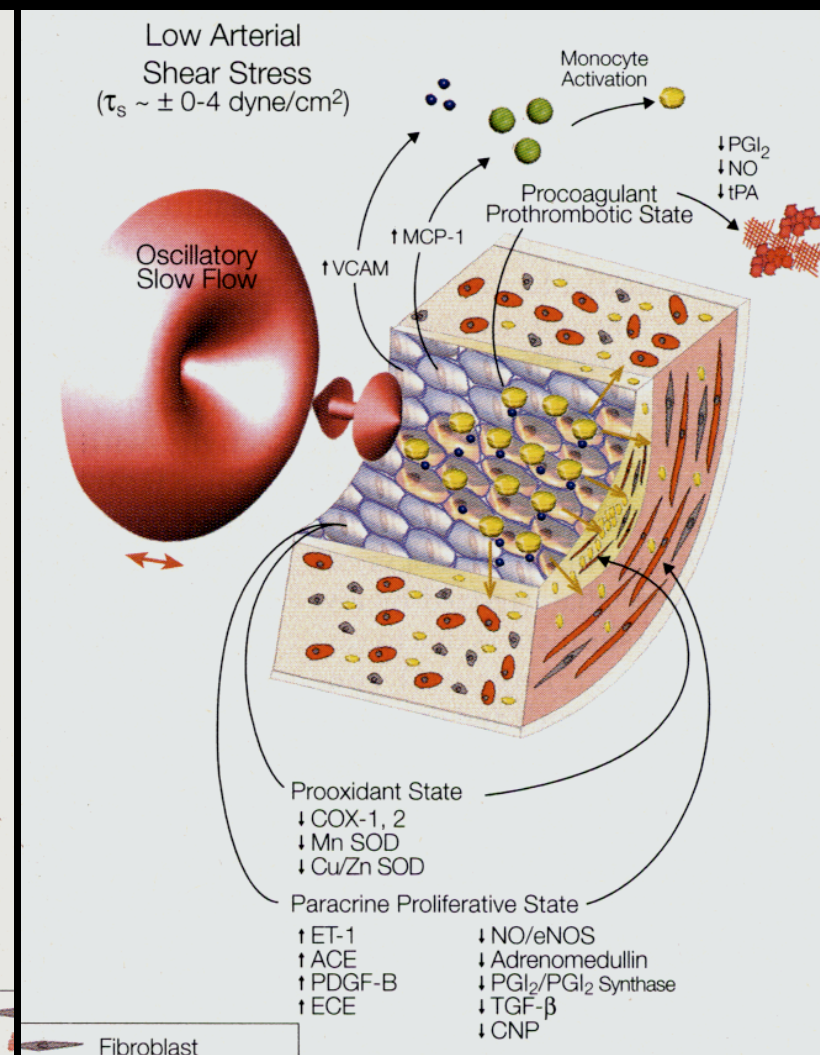
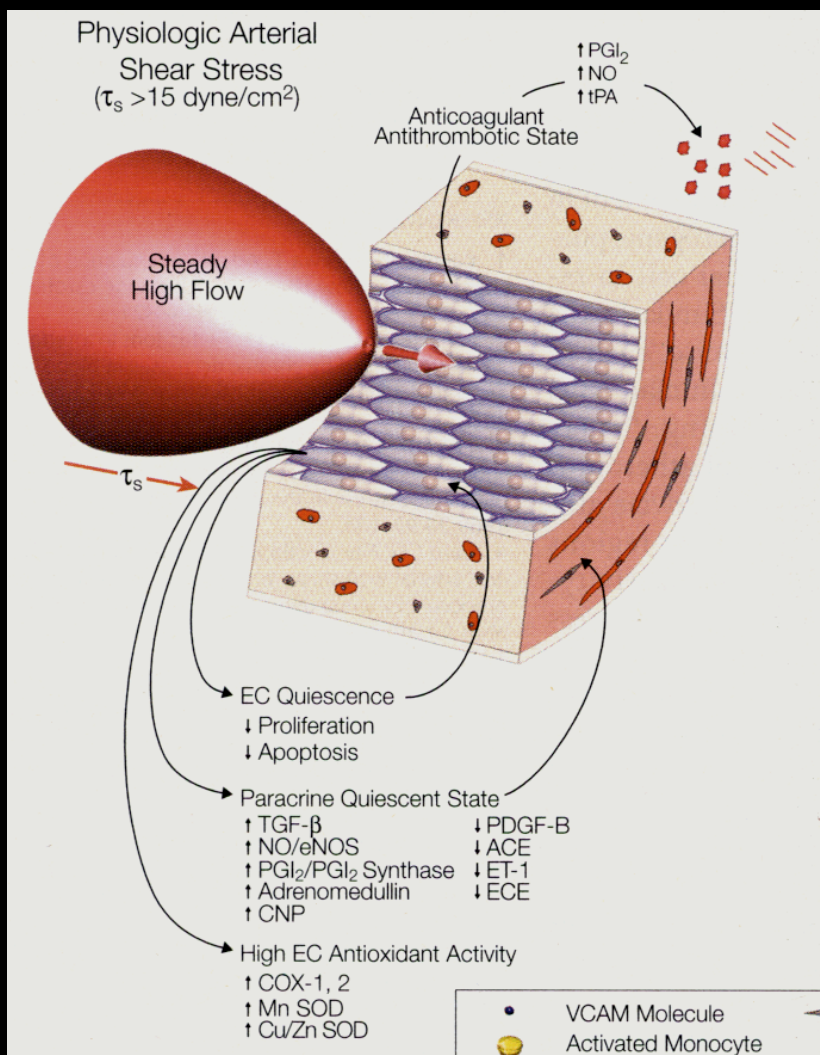
Static
Condition



Laminar
Flow



Mechanosensing and transduction



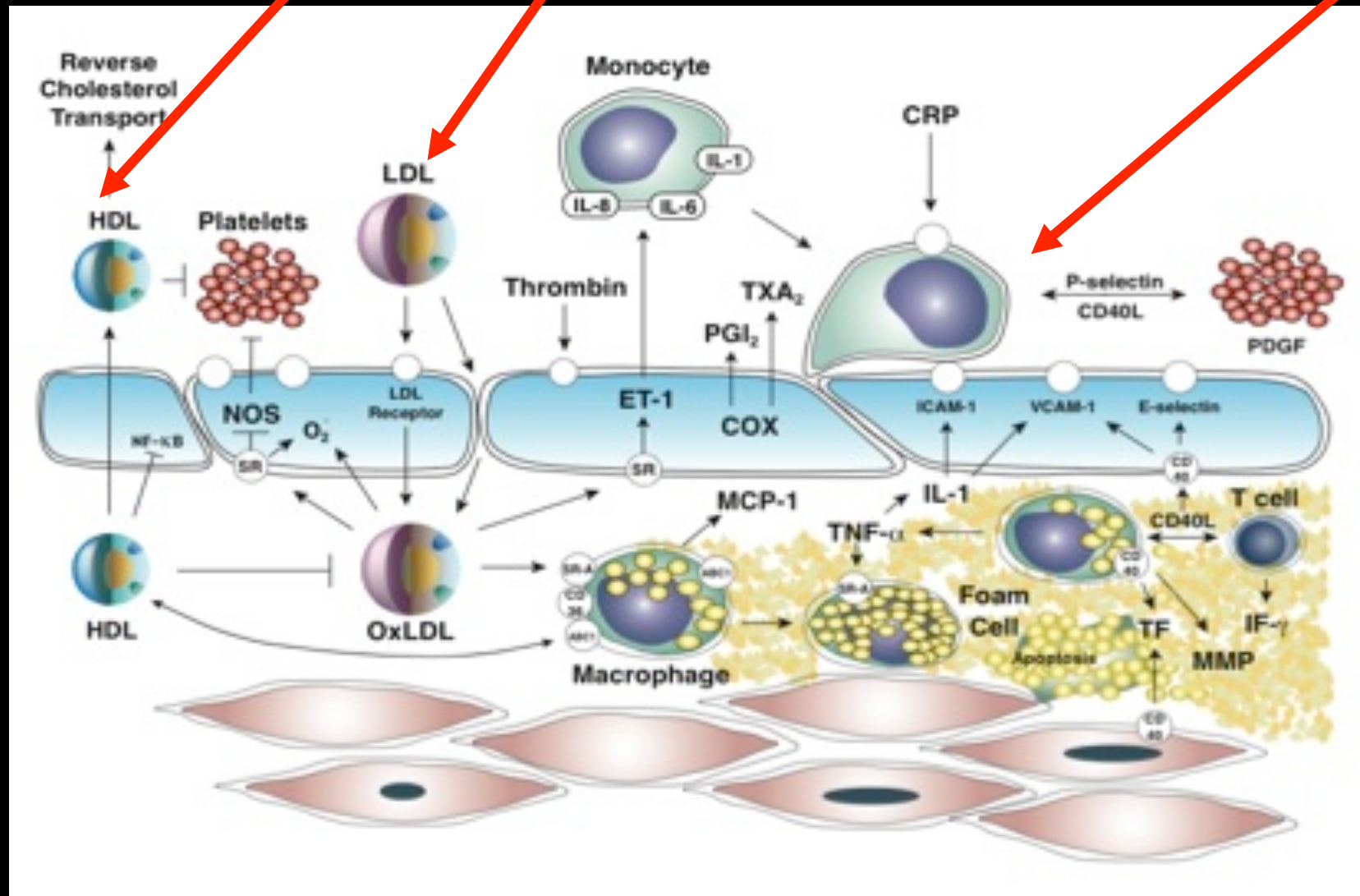
Vasculoprotective

Vascular adhesion of
lipoproteins &
inflammatory cells

Inflammatory response & Feedback

Cholesterol (HDL, LDL)

White blood cells



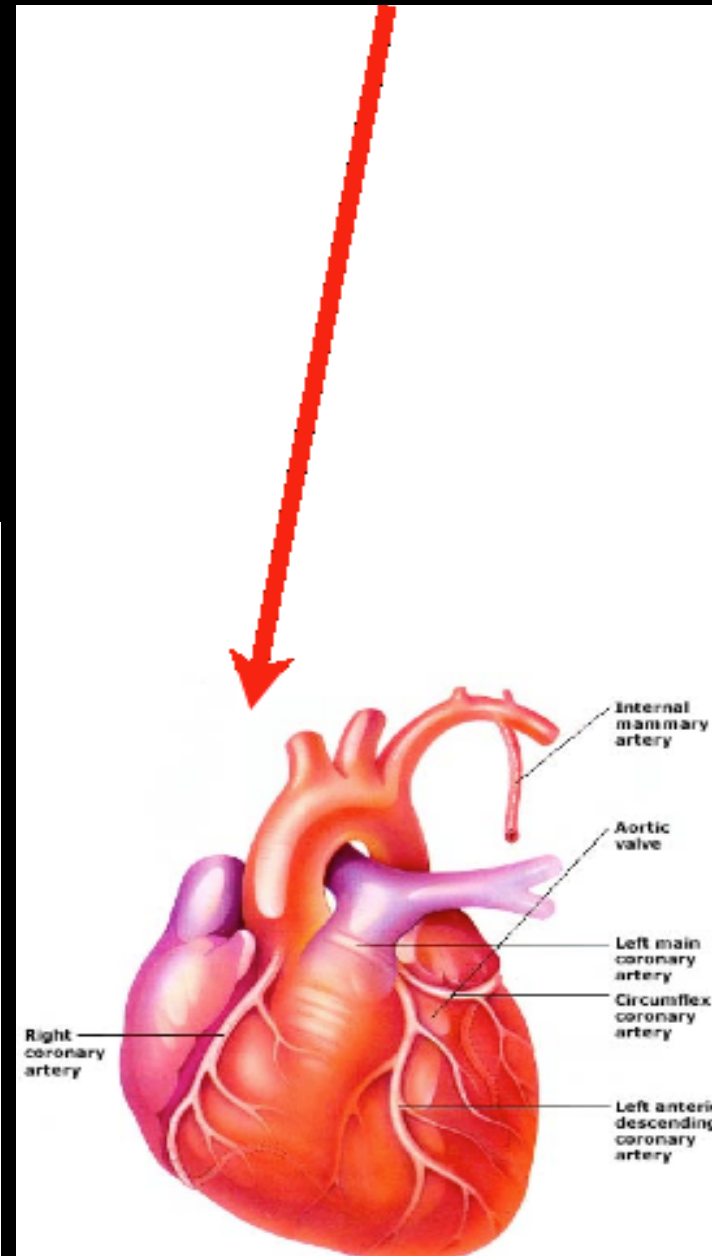
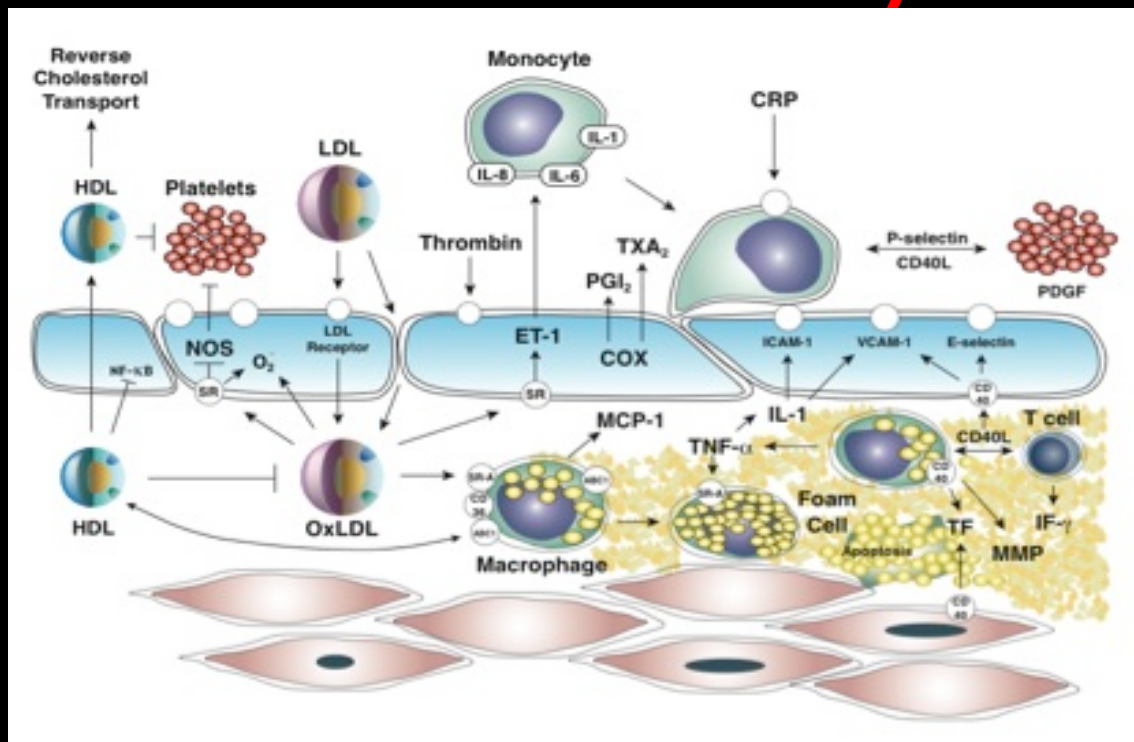
Endothelium

Muscle tissue

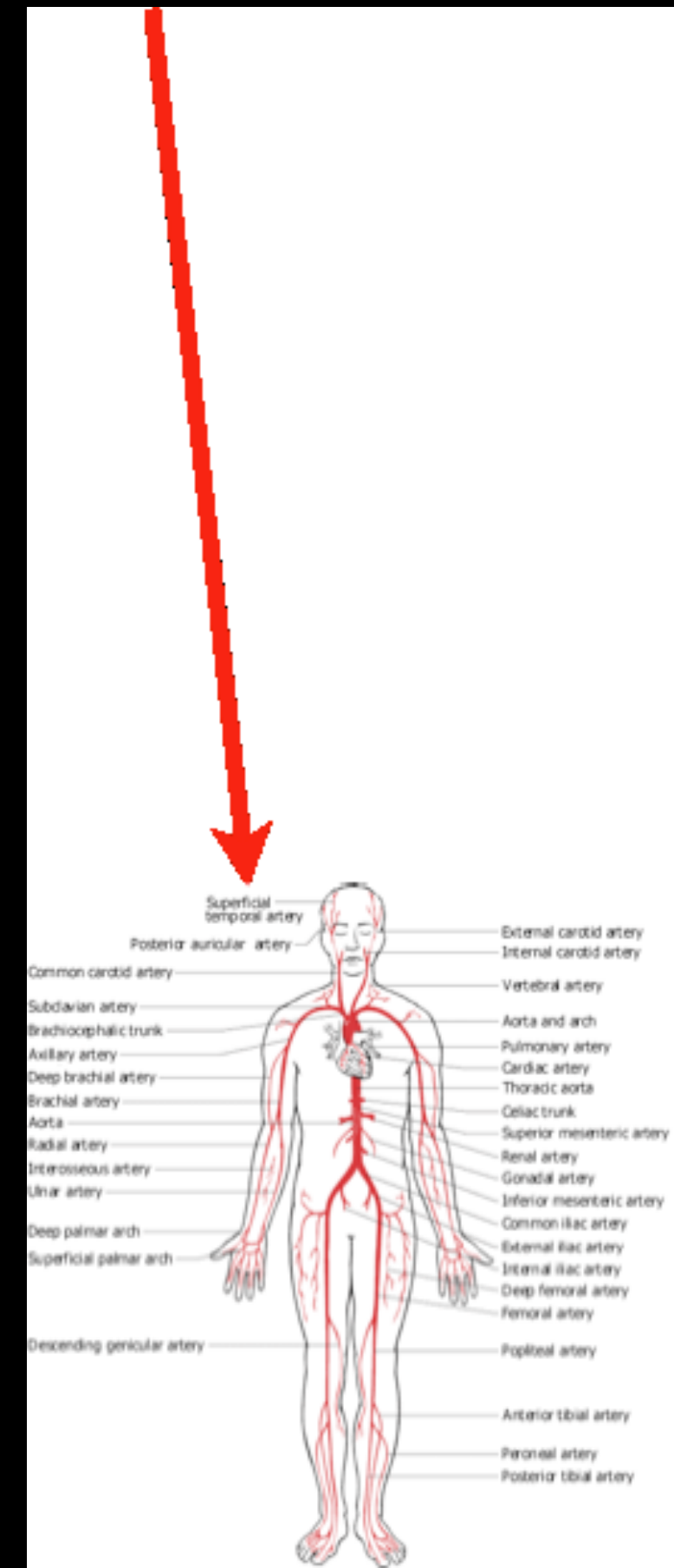
Grand Challenge: Multiscale

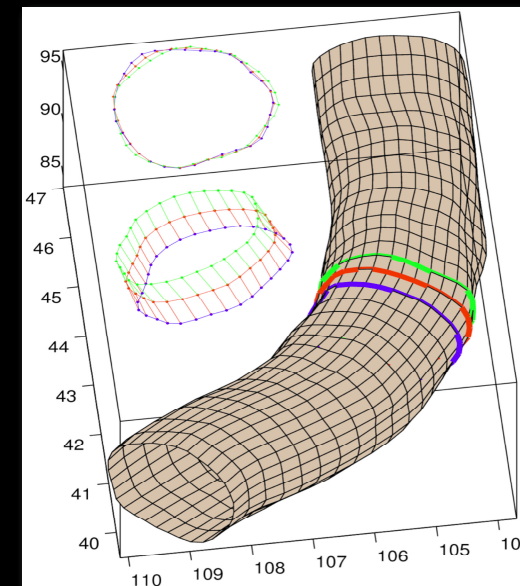
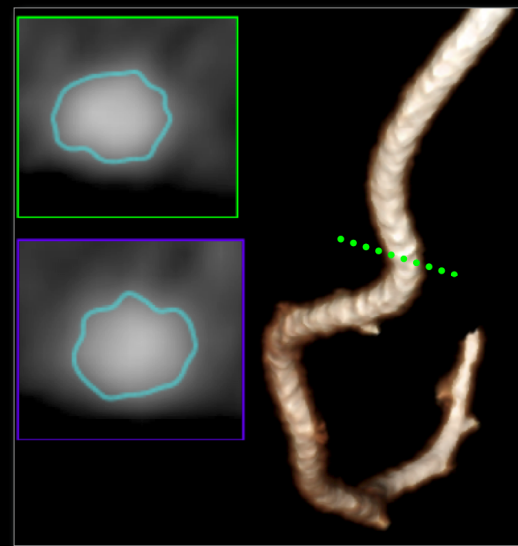
Hemodynamics cm-mm scale
– geometry/
fluid dynamics

$\mu\text{m-nm}$ scale
– biochemistry



m scale – BC's

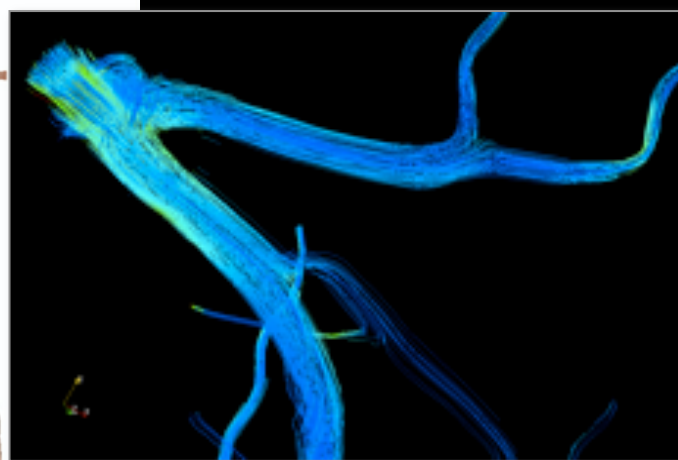
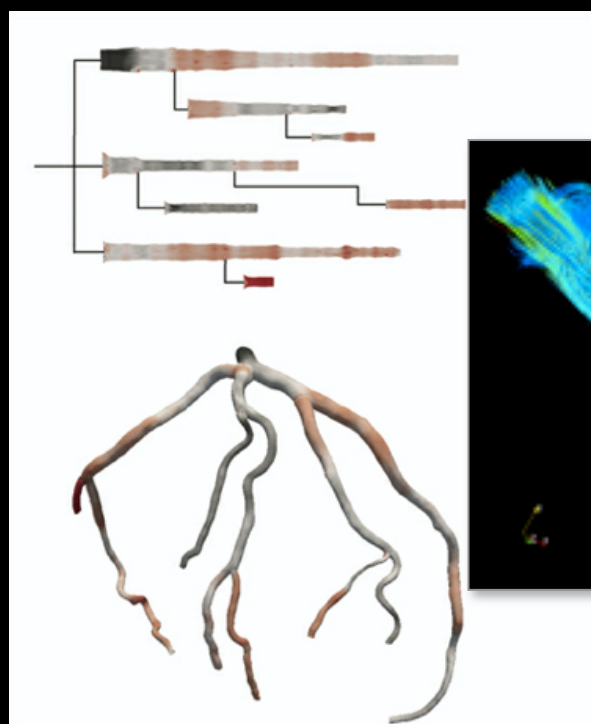




Patient Data → Data Segmentation → HPC Data Preparation



Parallel Code: MUPHY & HARVEY

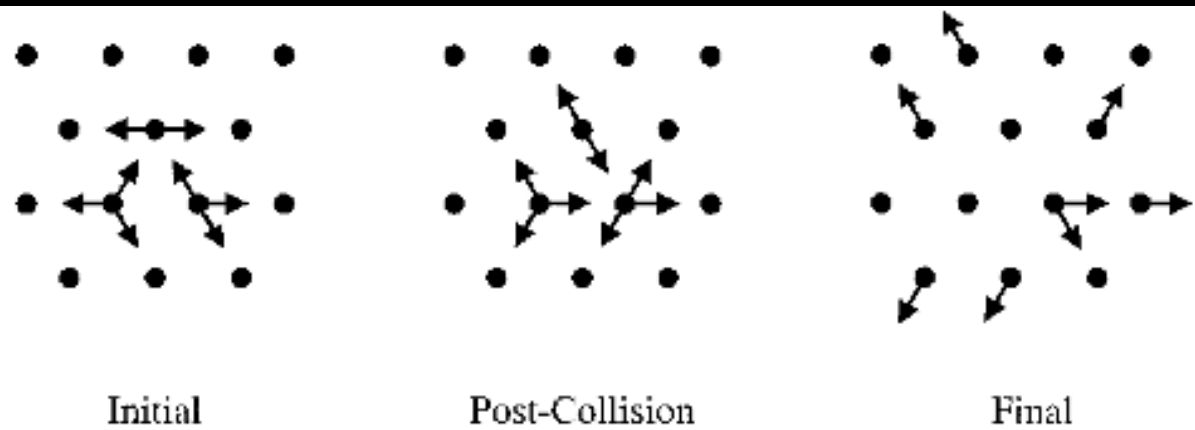


Output visualization



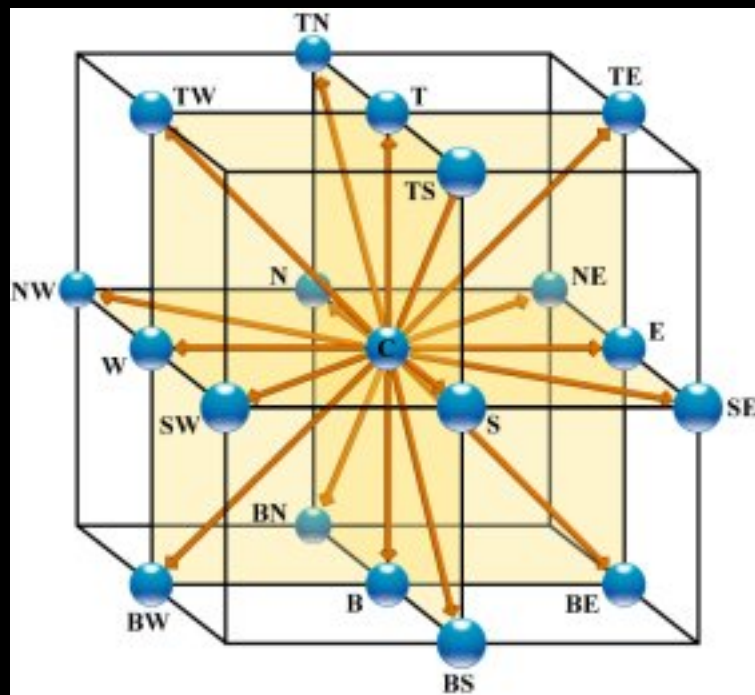
Fluid dynamics by cellular automata : Lattice Boltzmann Equation (LBE)

$$f_i(\vec{x} + \vec{c}_i \Delta t, t + \Delta t) = f_i(\vec{x}, t) - \omega \Delta t (f_i - f_i^{eq})(\vec{x}, t)$$



$$f_i^{eq} \propto \rho w_i \left[1 + \frac{\vec{c}_i \cdot \vec{u}}{c^2} + \frac{(\vec{c}_i \cdot \vec{u})^2 - c^2 u^2}{2c^4} \right]$$

Bhatnagar-Gross-Krook algorithm



Reproduces the physics
of fluid dynamics
(Navier-Stokes equation)

Fluid dynamics :

Fluid density

$$\rho(\vec{x}, t) = \sum_i f_i(\vec{x}, t)$$

Momentum (flow)

$$\rho(\vec{x}, t) \vec{u}(\vec{x}, t) = \sum_i f_i(\vec{x}, t) \vec{c}_i$$

Stress Tensor

$$\vec{\sigma}(\vec{x}, t) = \frac{\nu \omega}{c_s^2} \sum_i \vec{c}_i \vec{c}_i \left[f_i - f_i^{eq} \right](\vec{x}, t)$$

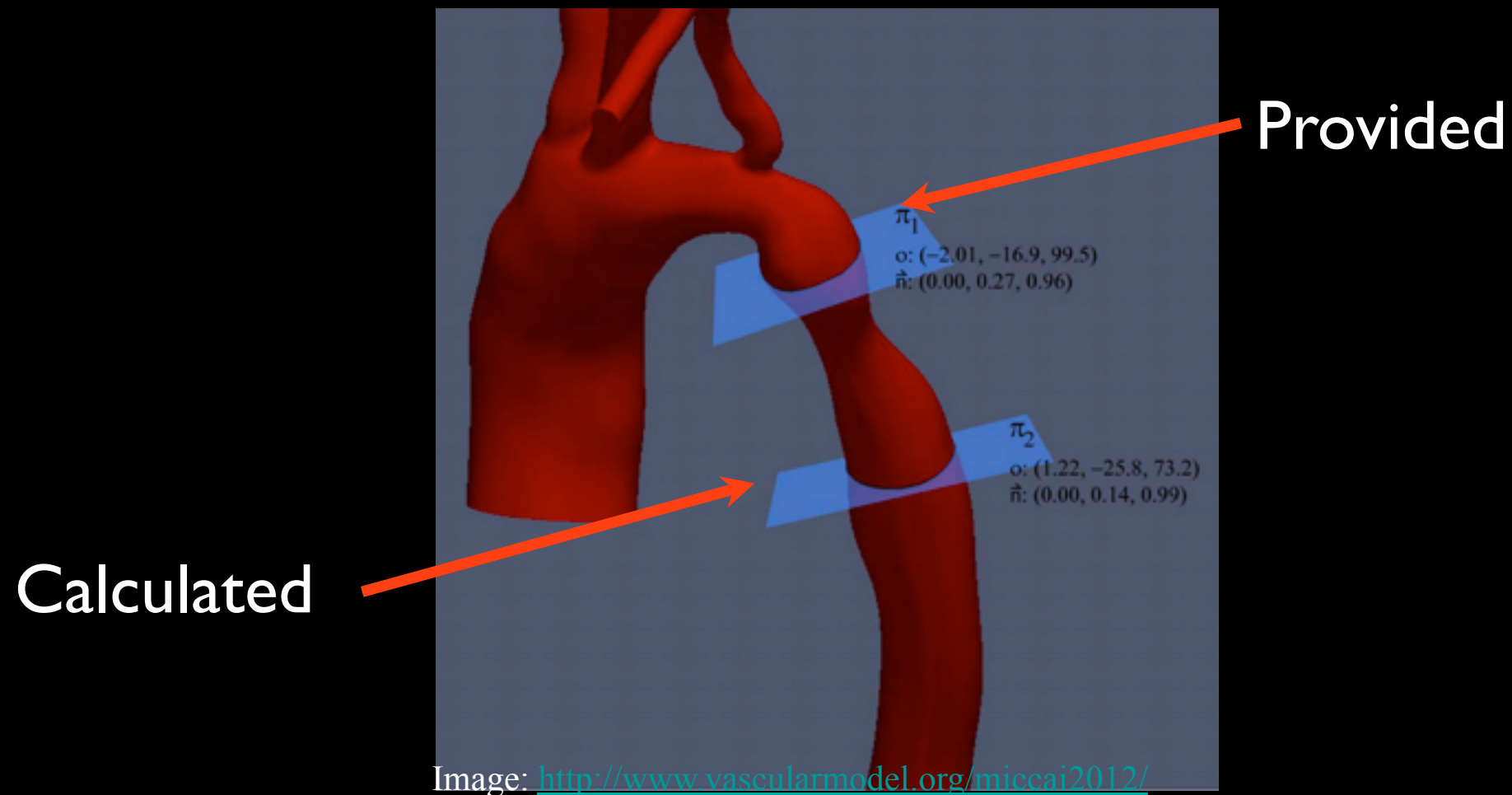
Wall Stress

$$S(\vec{x}_w, t) = \sqrt{(\vec{\sigma} : \vec{\sigma})(\vec{x}_w, t)}$$

Advantages of Lattice Boltzmann

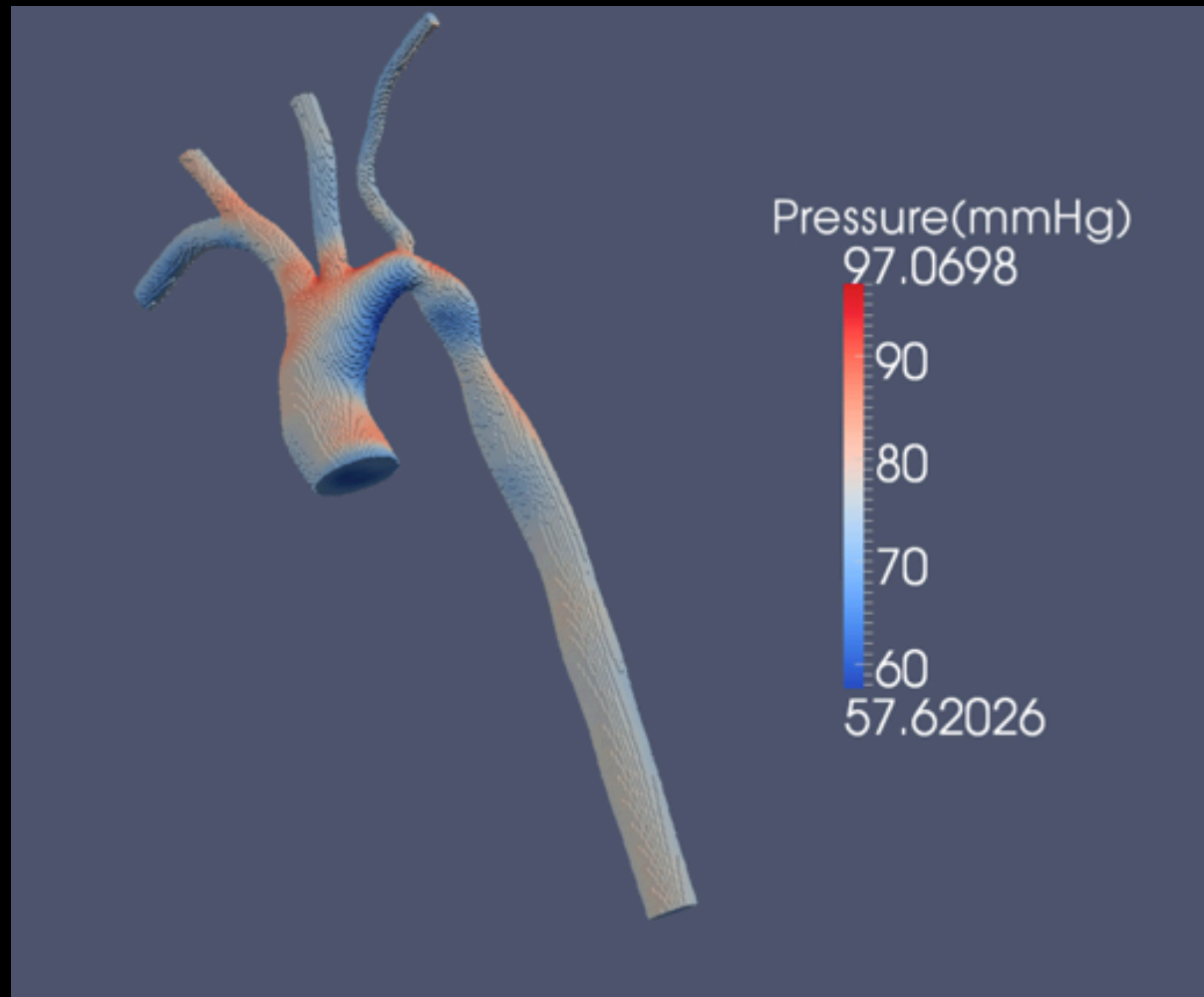
- Simple, time-explicit, robust, and accurate algorithm
- Straight forward handling of extremely complex geometries
- Recovers Navier-Stokes equations
- Data locality (helps parallel implementation)
- Computational simplicity (cubic grid)

Accuracy of flow patterns for real, patient-specific geometries



STACOM Computational Fluid Dynamics Challenge

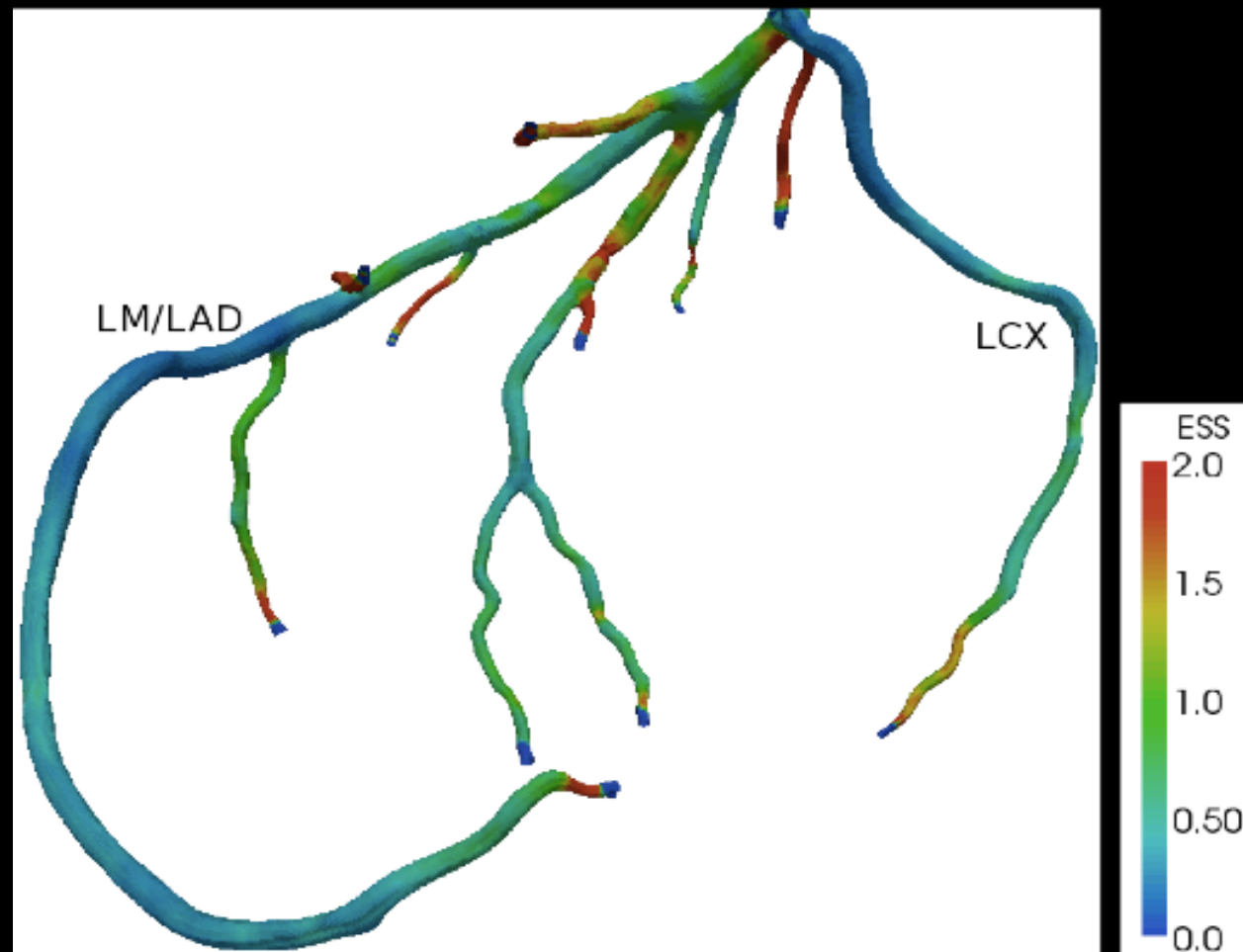
Comparison with *in vivo* measurements



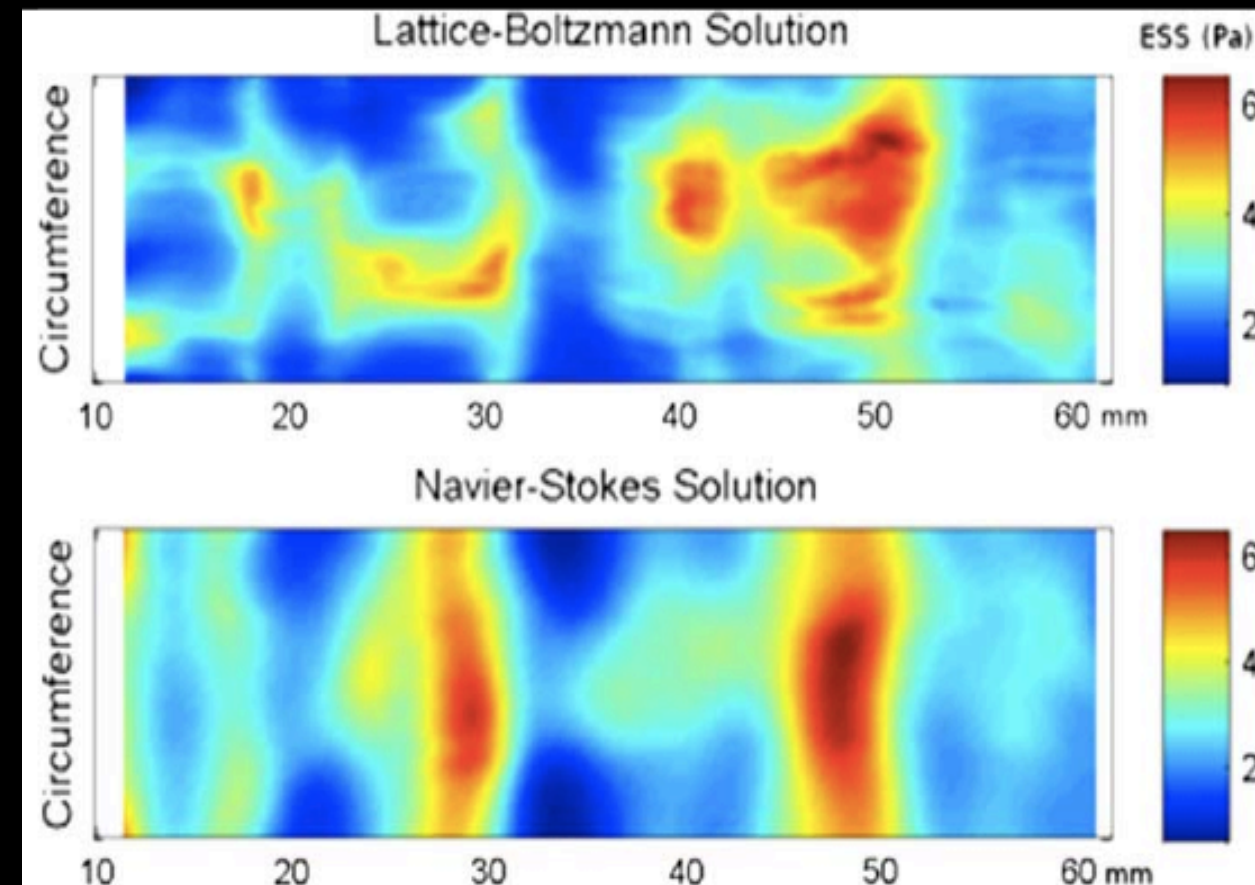
Peters Randles et. al. LNCS, 2013

- Convergence of pressure at 20 microns
- 2 mmHg change between diastole and systole
- Mean pressure difference of 9.2 mmHg
- **Best mean pressure drop in the competition**

ESS calculation in patient-specific arterial tree



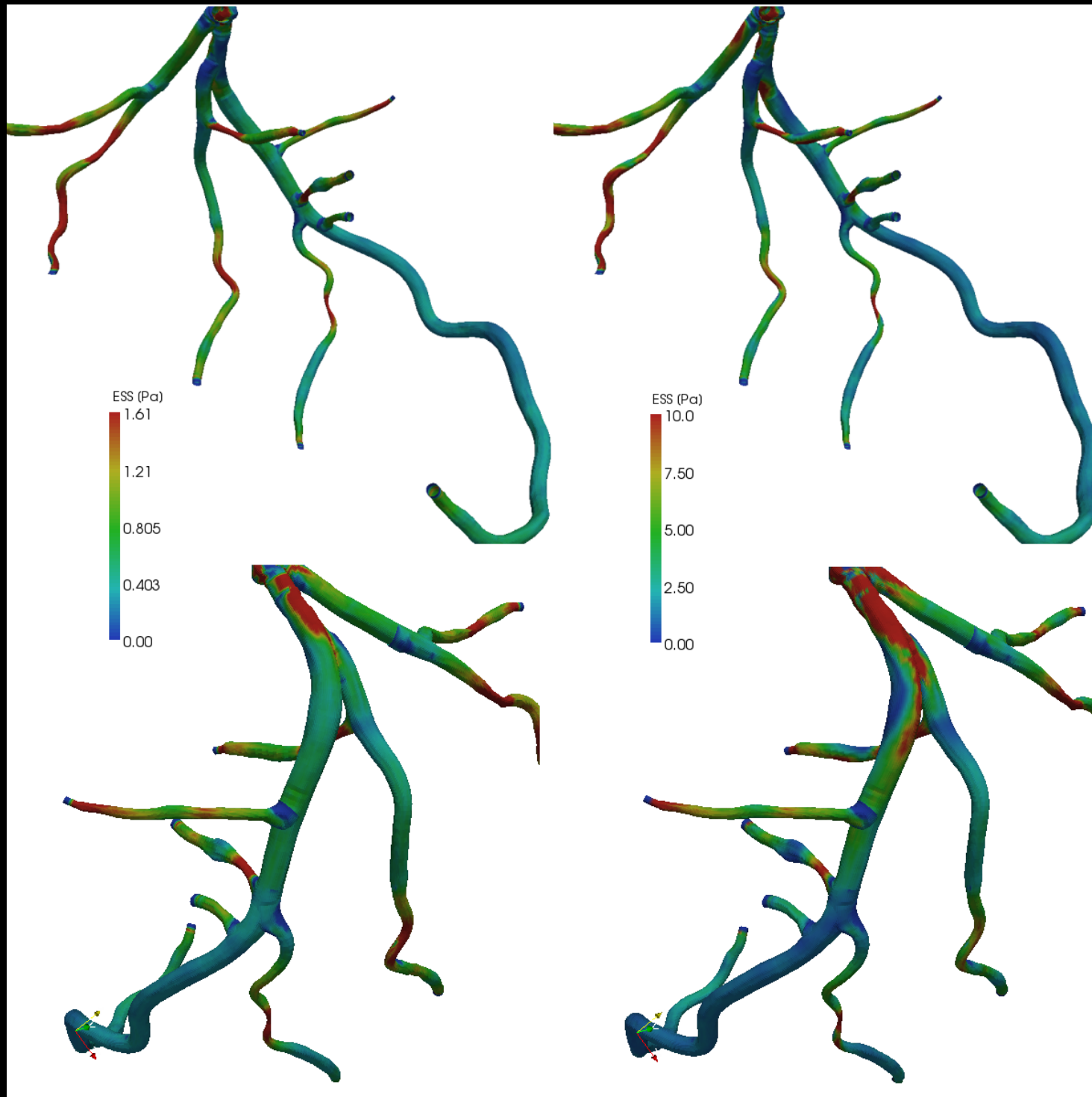
Validation



3D ESS maps at different flow conditions

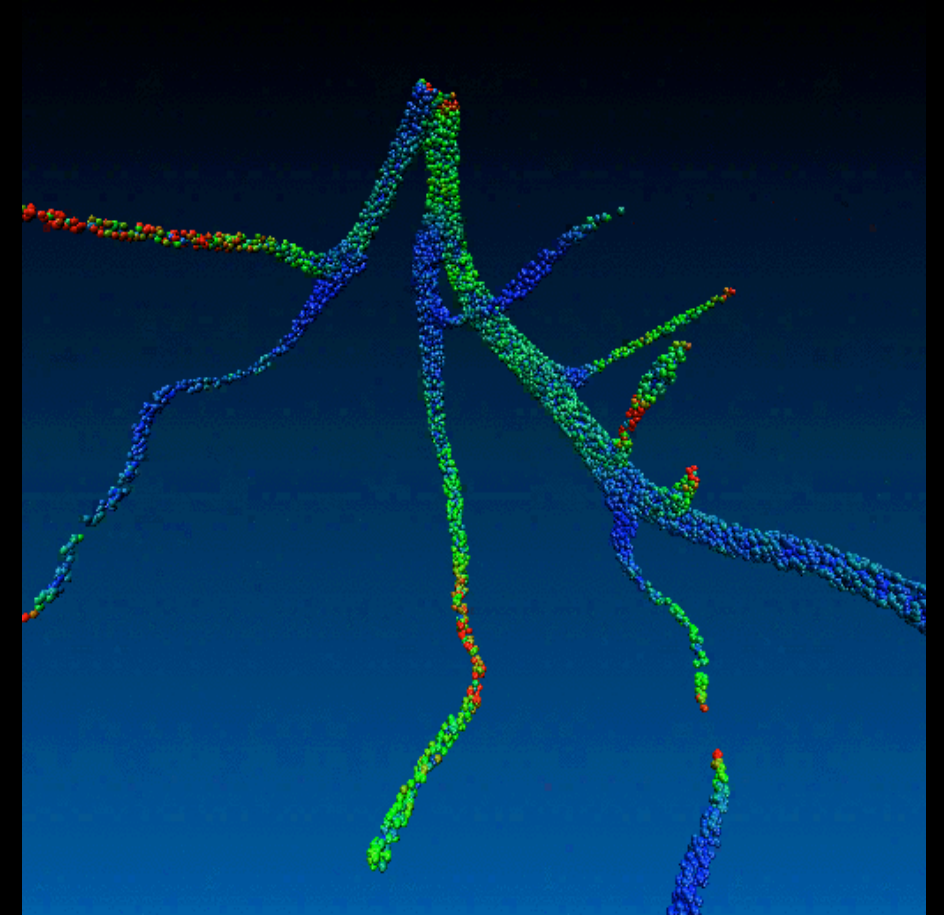
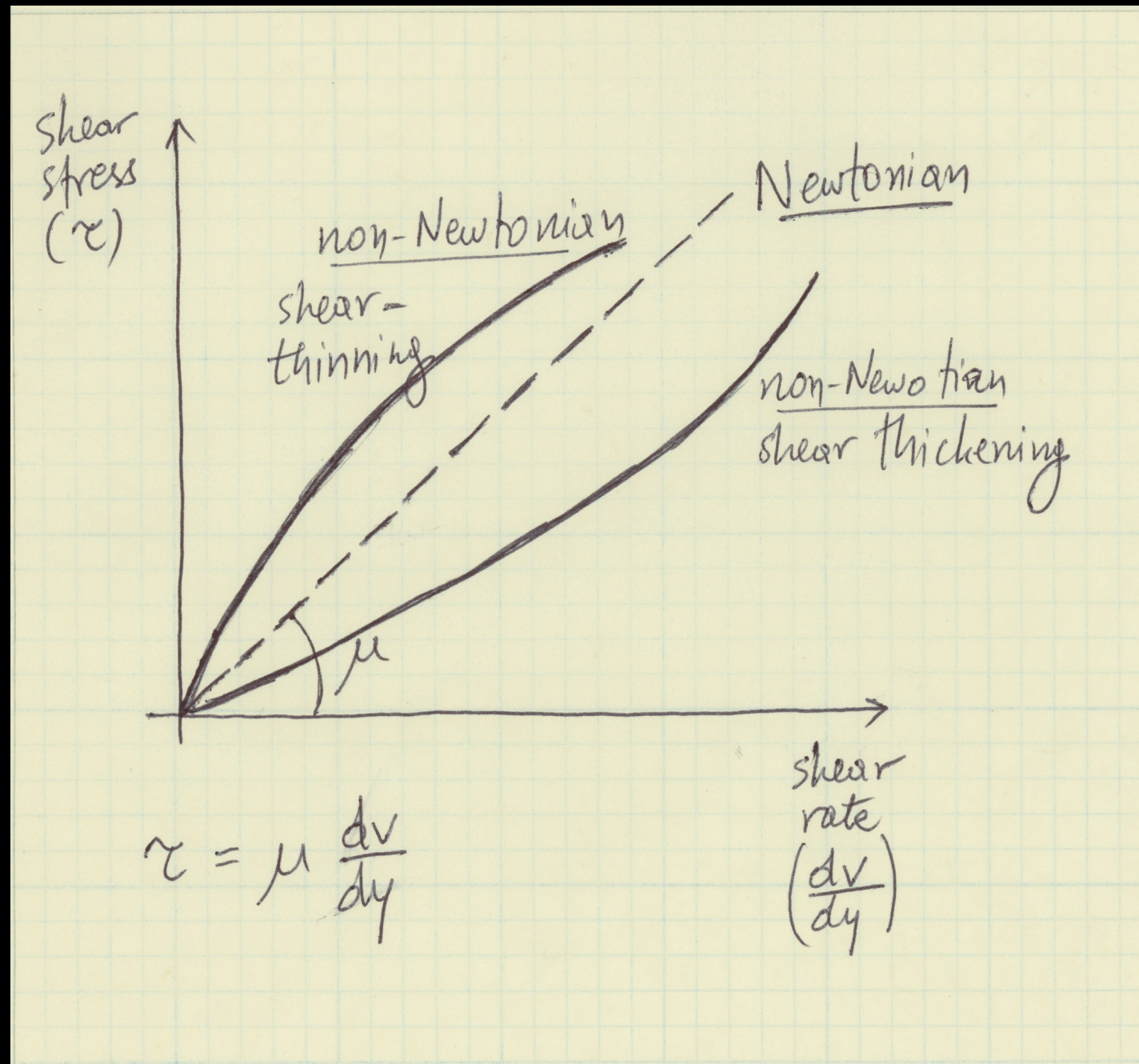
Low flow

High flow

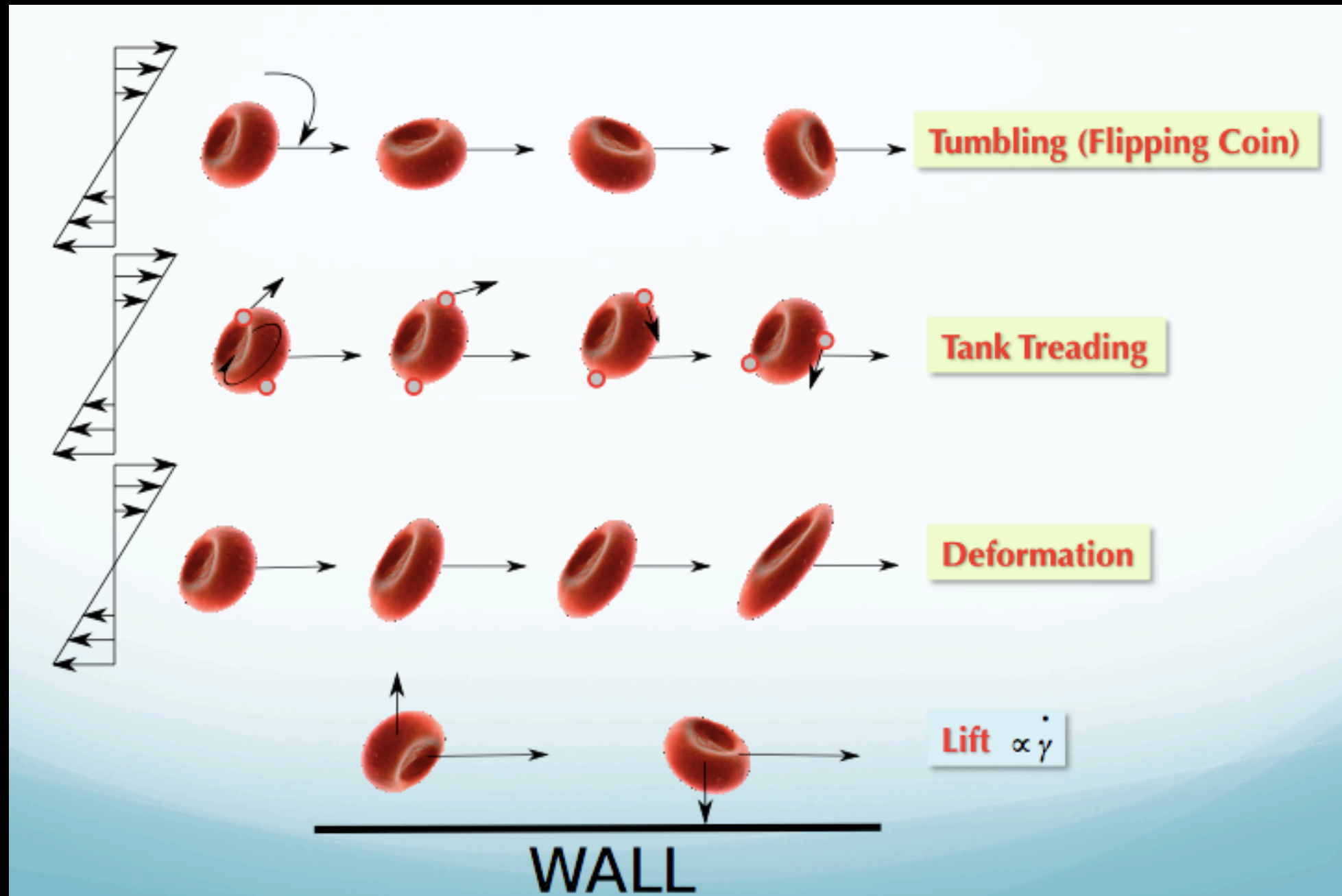


Full heart beat (1 sec,
~ 10^6 simulation steps)

Challenge: non-Newtonian nature of blood



Red Blood Cell in Motion



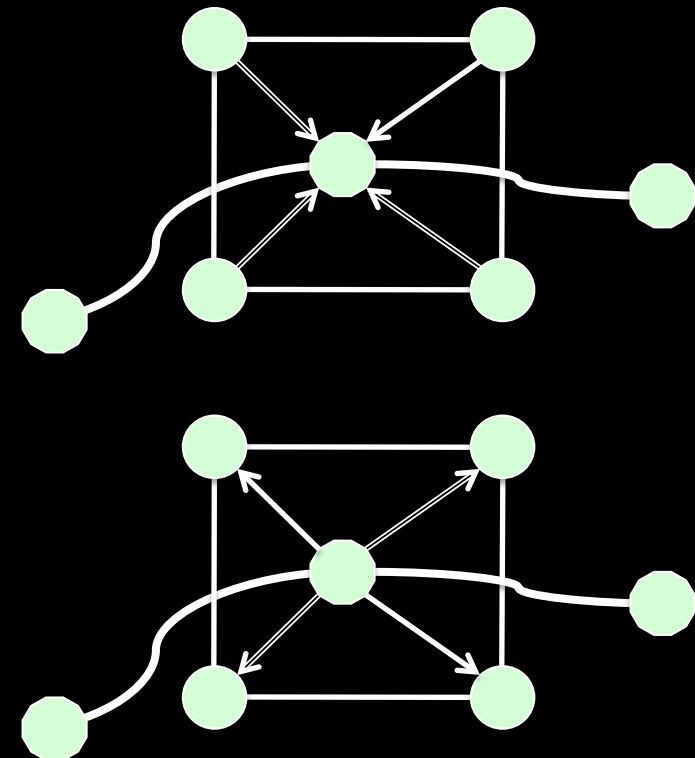
Coupling of particle and fluid (continuum) scales

$$(\partial_t + v \cdot \partial_x) f = -\omega(f - f^{eq}) - \frac{1}{M} \sum_R F^H \cdot \partial_v f$$

$$\frac{d}{dt} V = \frac{1}{M} (F + F^H)$$

$$F^H = -\gamma [V - u(x, \{R, V\})] \delta(x - R)$$

Momentum exchange
(Newton's law)

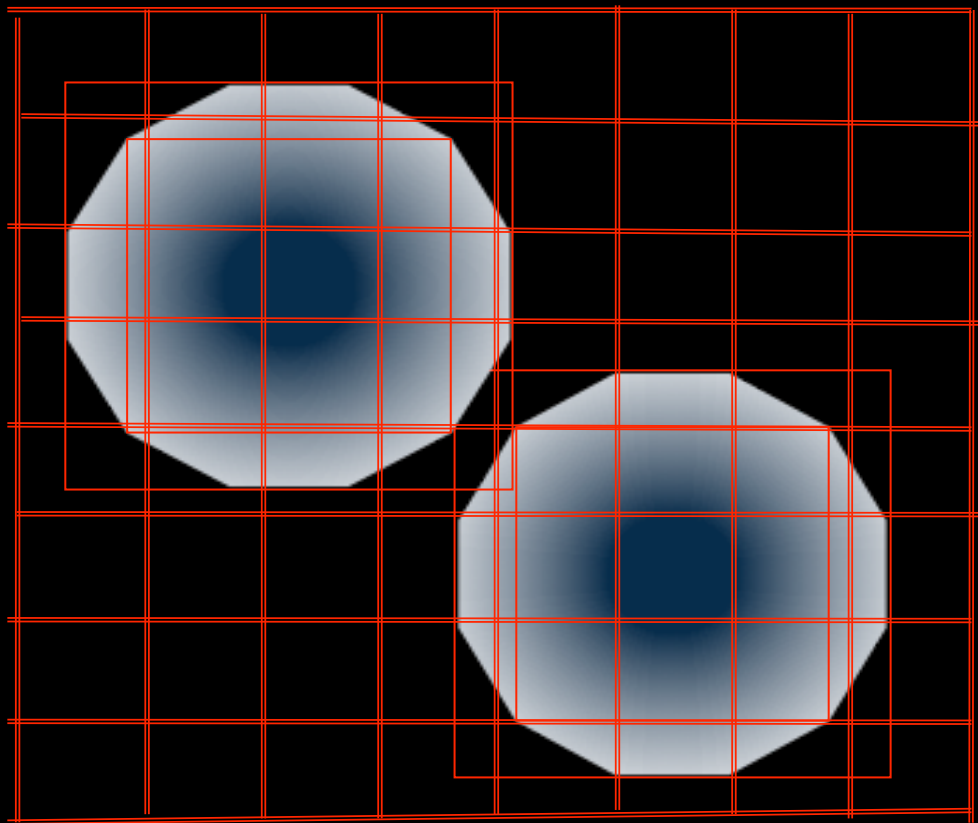


Definition of particles (cells, proteins, ...)

$$\tilde{\delta}_{\xi}(x - R) = \prod_{\alpha=x,y,z} \tilde{\delta}_{\xi}(x_{\alpha} - R_{\alpha})$$

$$\sum_x \tilde{\delta}_{\xi}(x - R) = 1$$

$$\tilde{\delta}_{\xi}(a) = \begin{cases} \frac{1}{2\xi} \left(1 + \cos\left(\frac{\pi|a|}{\xi}\right) \right) & 0 \leq |a| \leq \xi \\ 0 & \xi \leq |a| \end{cases}$$



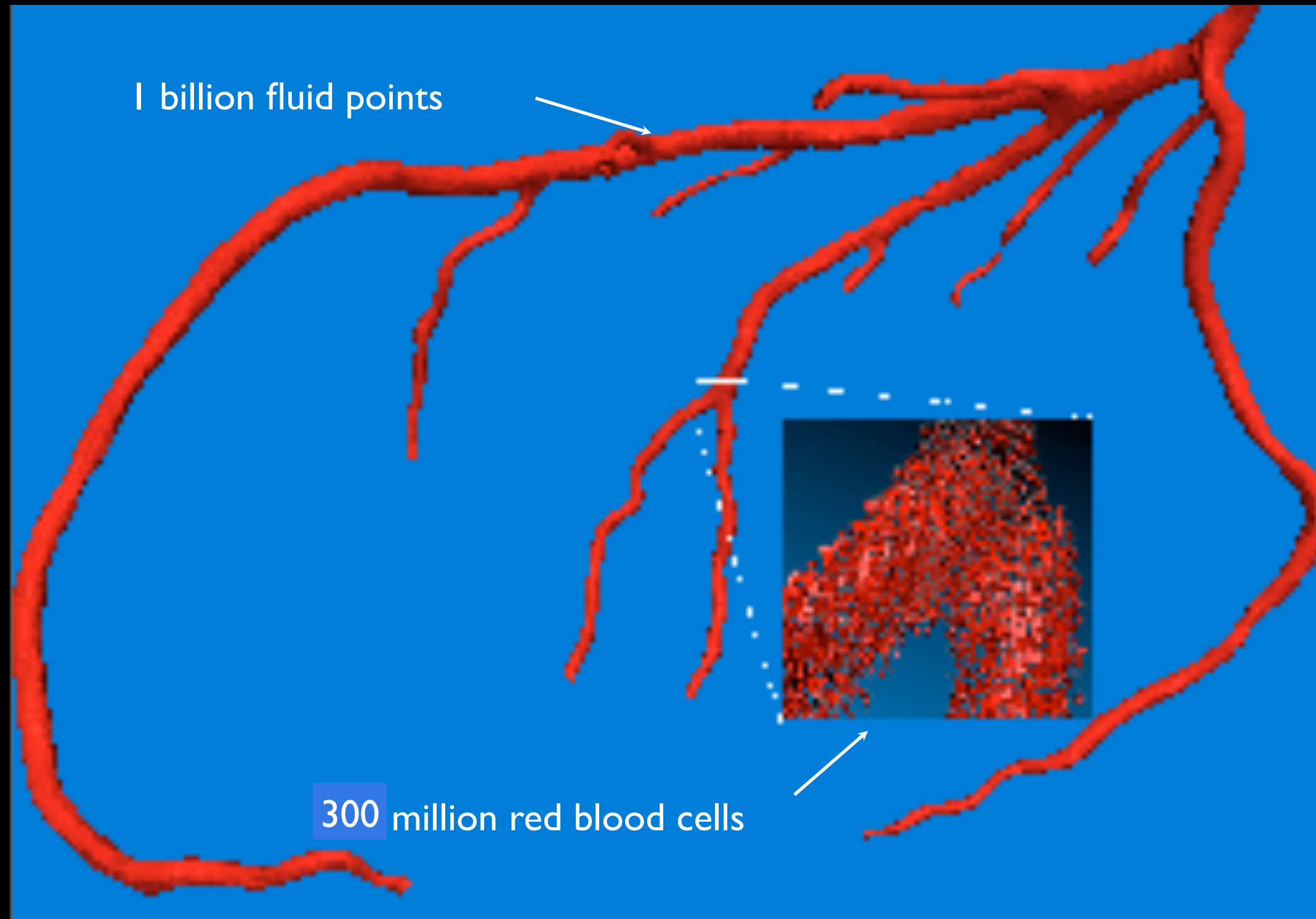
$$\varphi(x, R) = -\gamma(V - u(x)) \tilde{\delta}_{\xi}(x - R)$$

$$F^H = \sum_x \varphi = -\gamma(V - \tilde{u})$$

$$\tilde{u} = u * \tilde{\delta}_{\xi}$$

$$\Delta f_p = -\frac{w_p}{c^2} c_p \cdot \sum_R \varphi$$

Full artery simulation: computationally demanding



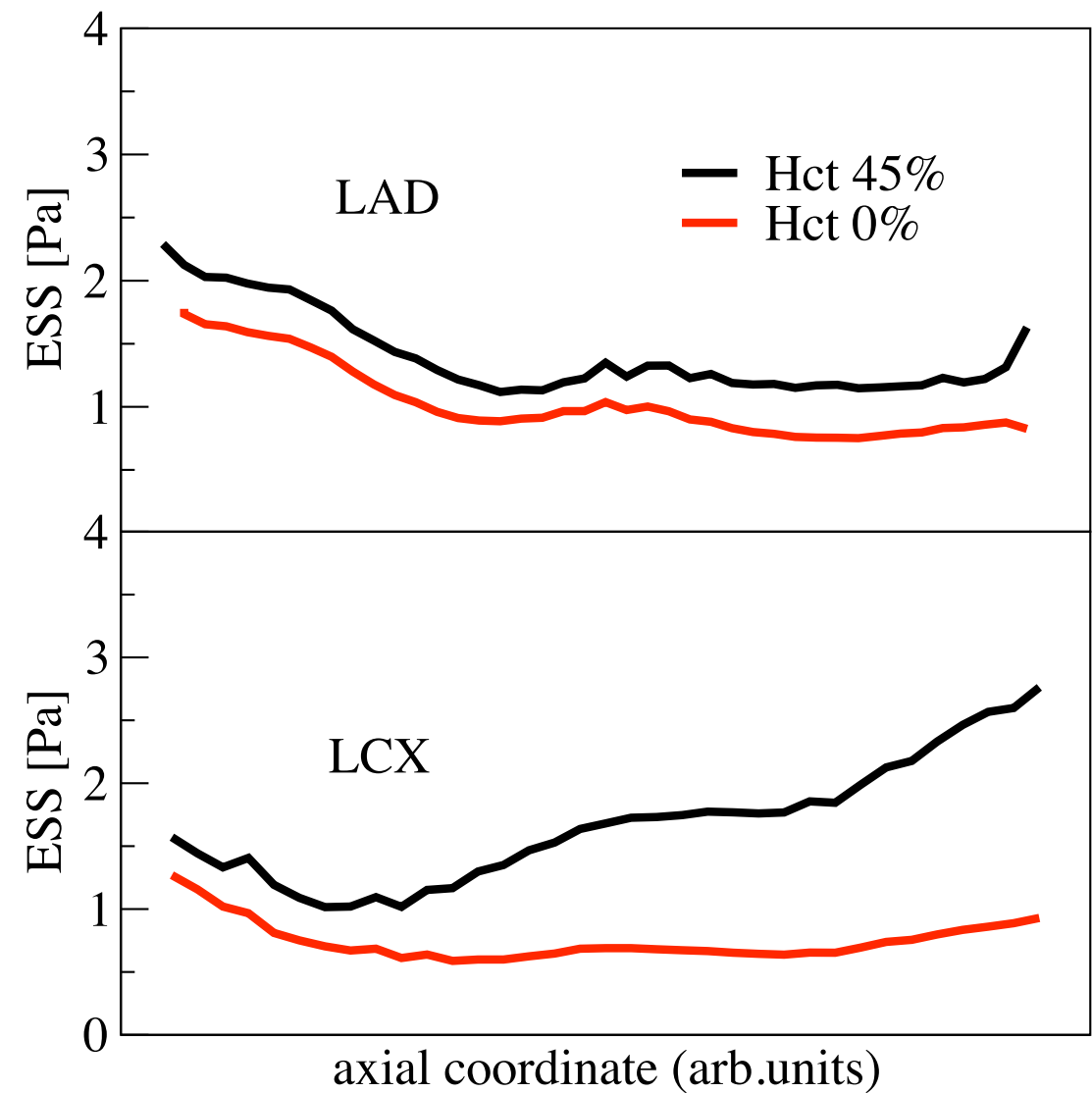
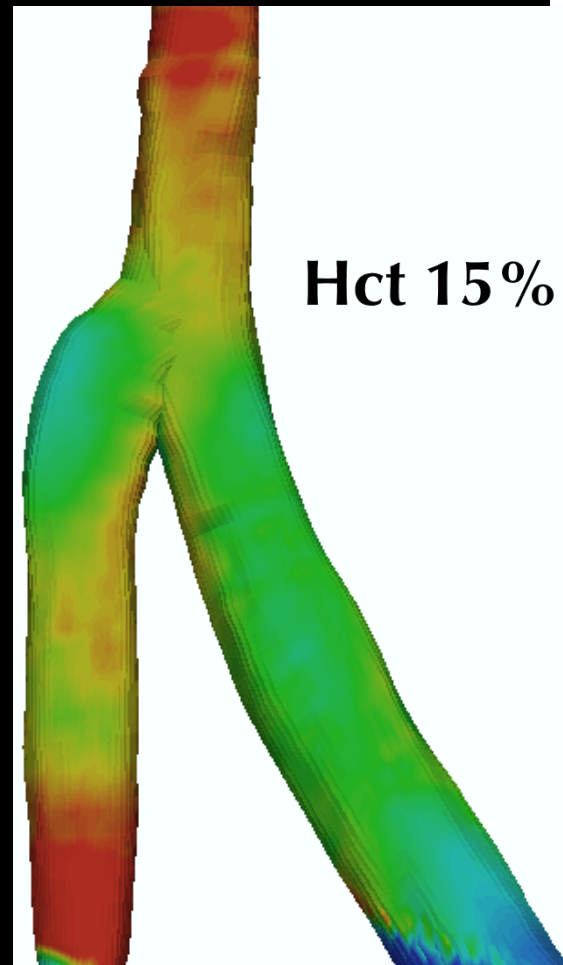
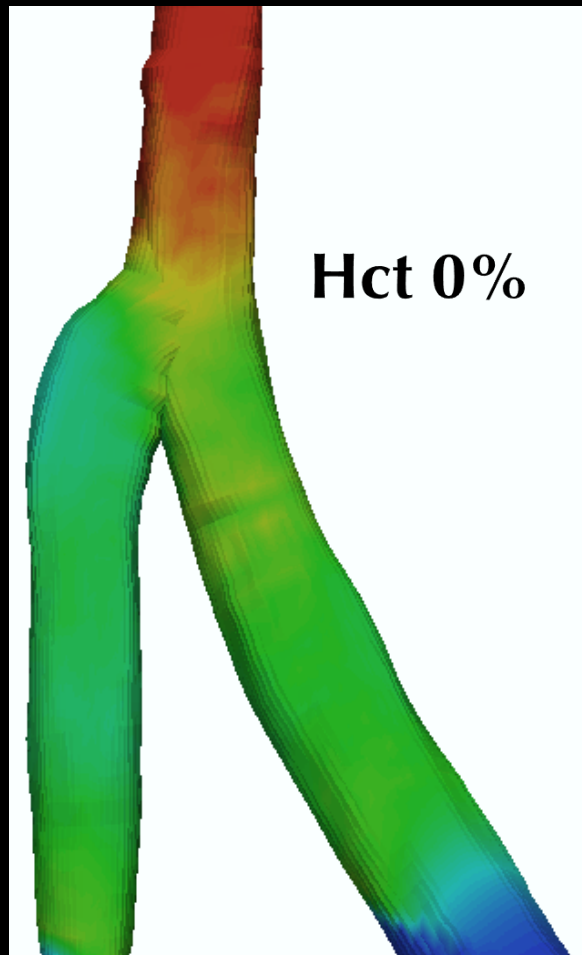


Full heartbeat simulation

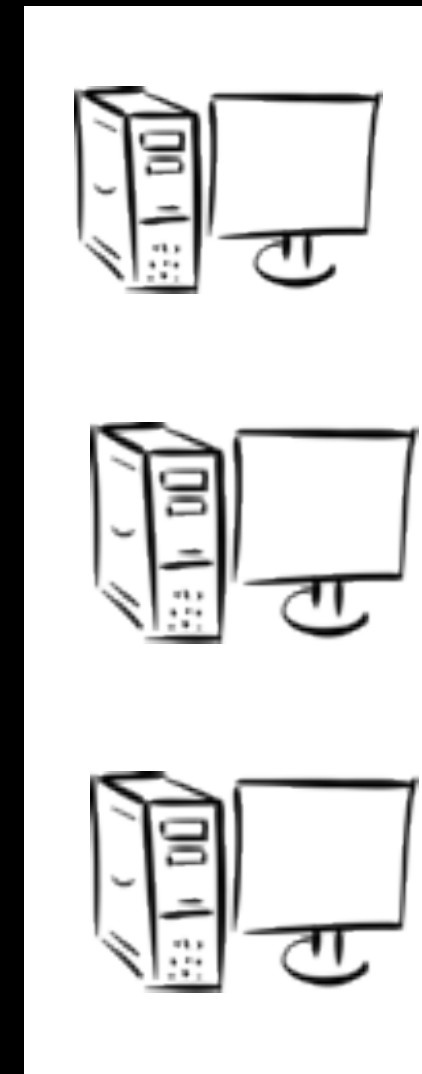
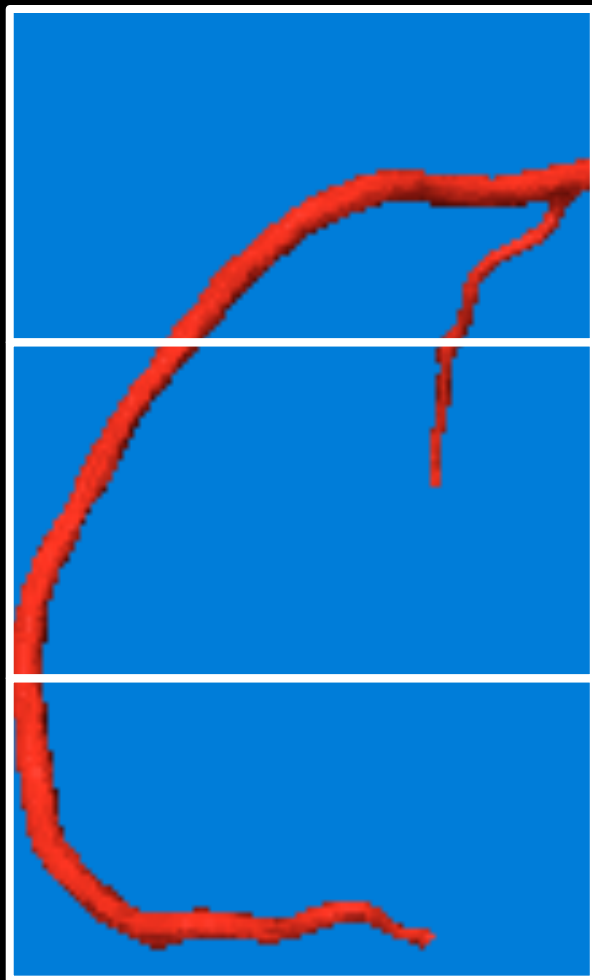
- Average of 0.7 seconds
- 300 million RBC's
- 294,912 processors
- Simulation took:
 - 6 hours
 - 2,000,000 compute hours



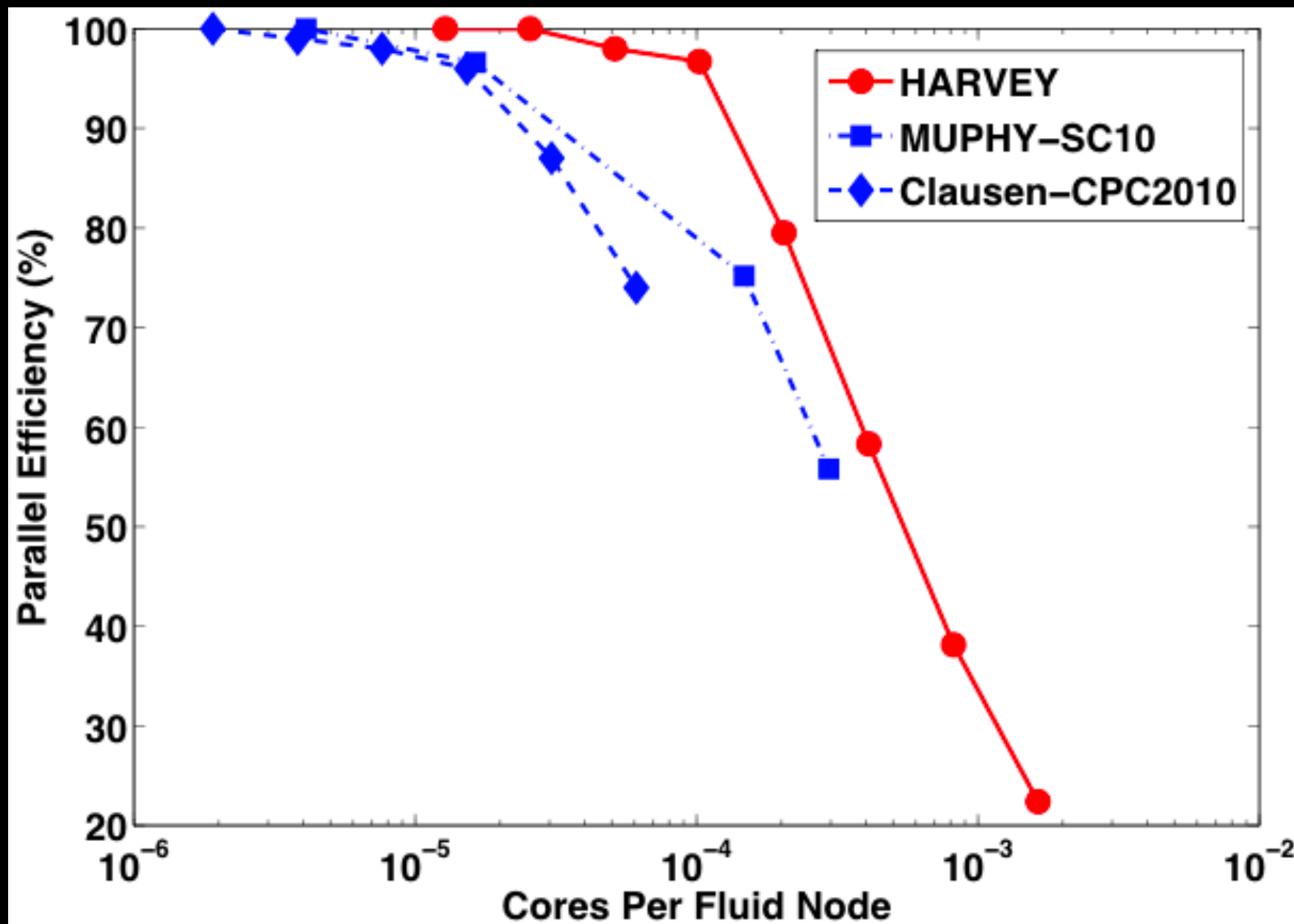
Effect of particle motion on ESS:



So far: spatial decomposition



Spatial Scaling Limit



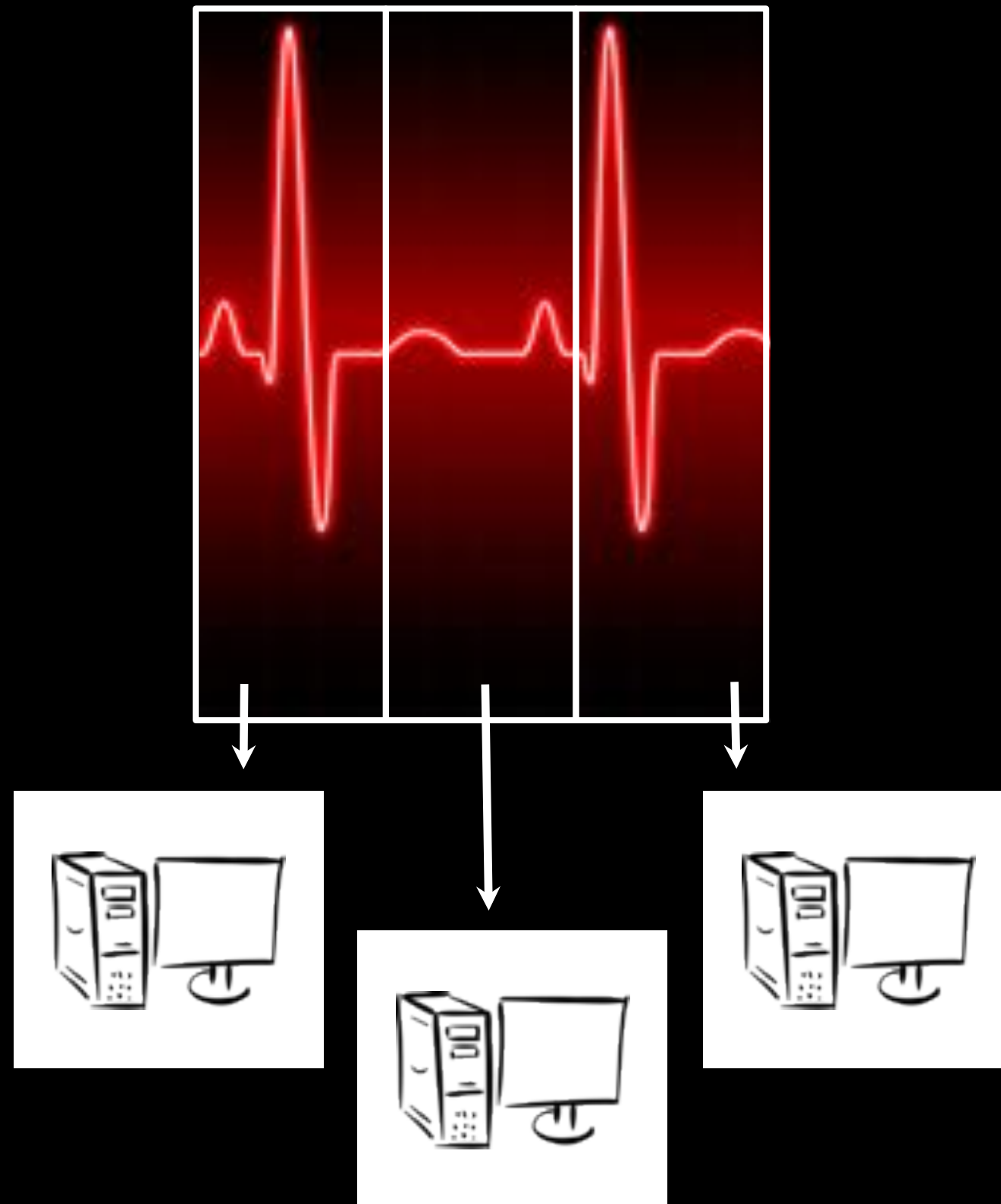
Peters Randles, et al. Supercomputing, 2013 (submitted)

Peters Randles, et al. IPDPS 2013

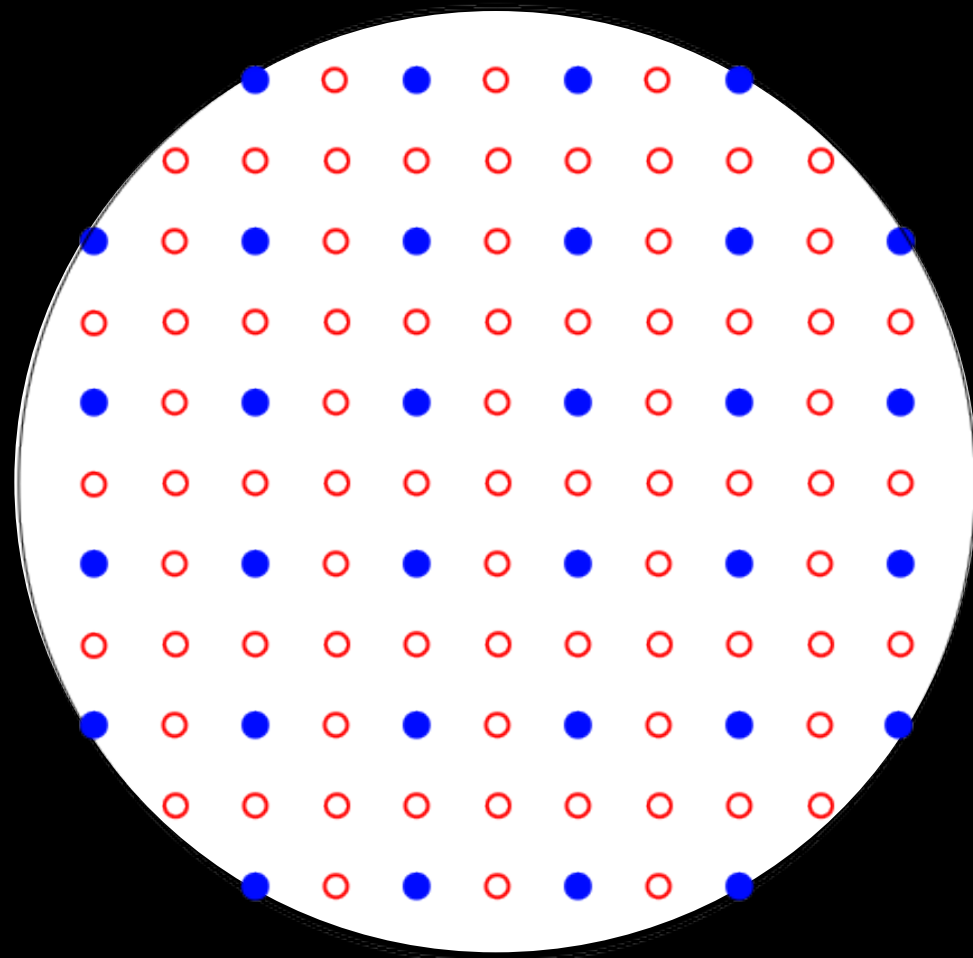
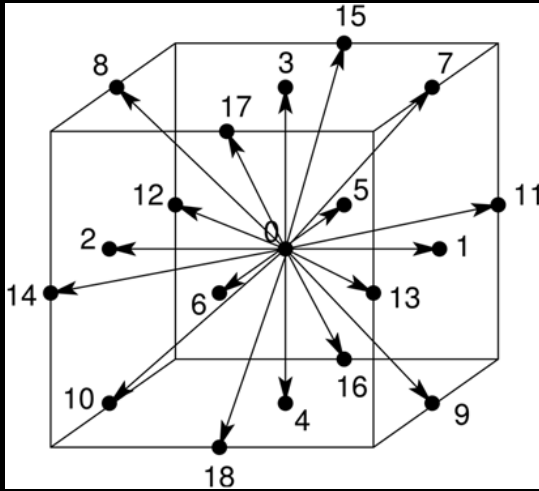
Peters, et al. Supercomputing, 2010

Clausen, et al. Computer Physics Communications, 2010

Goal: reduce wallclock time by parallel-in-time simulations

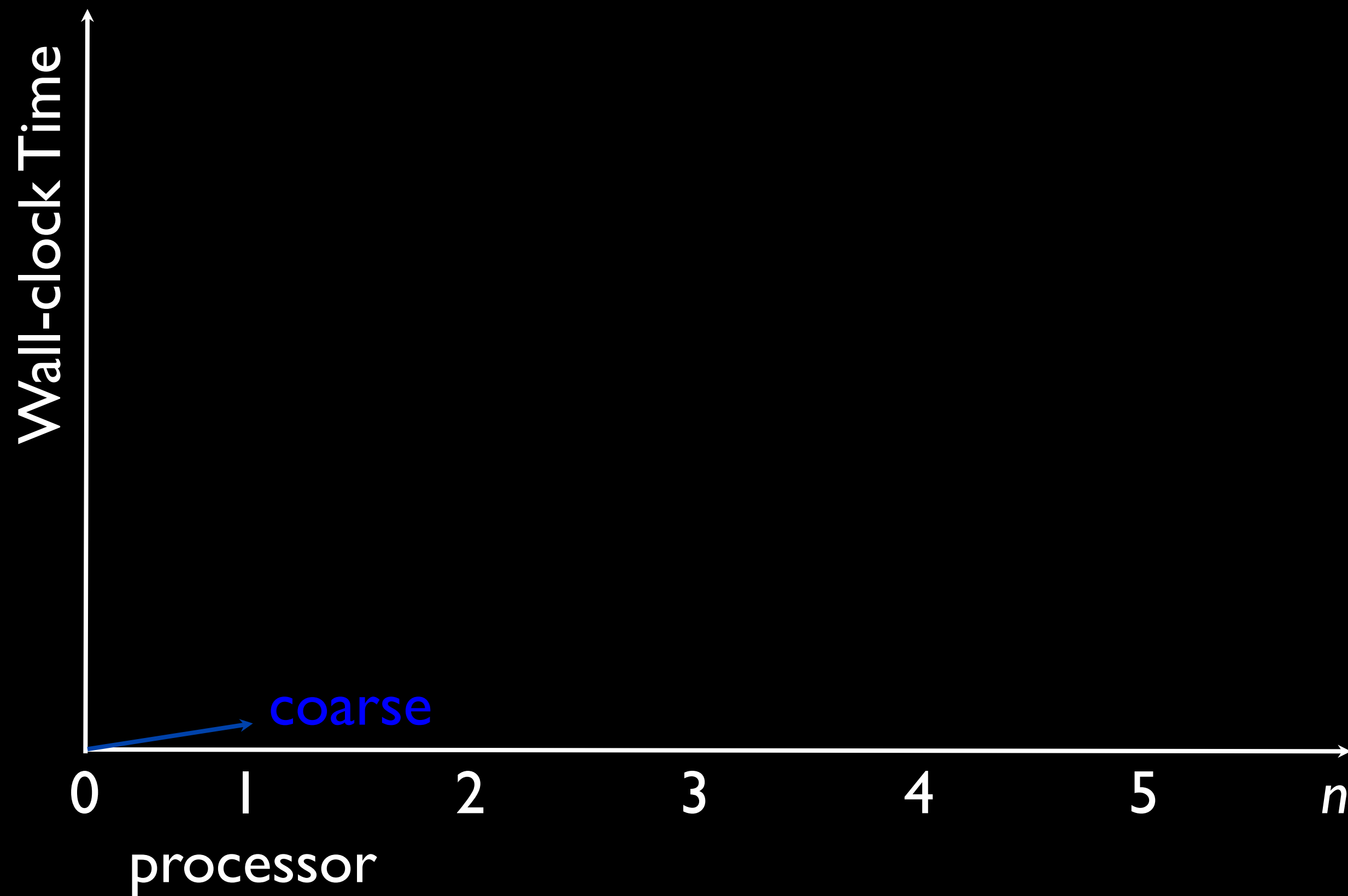


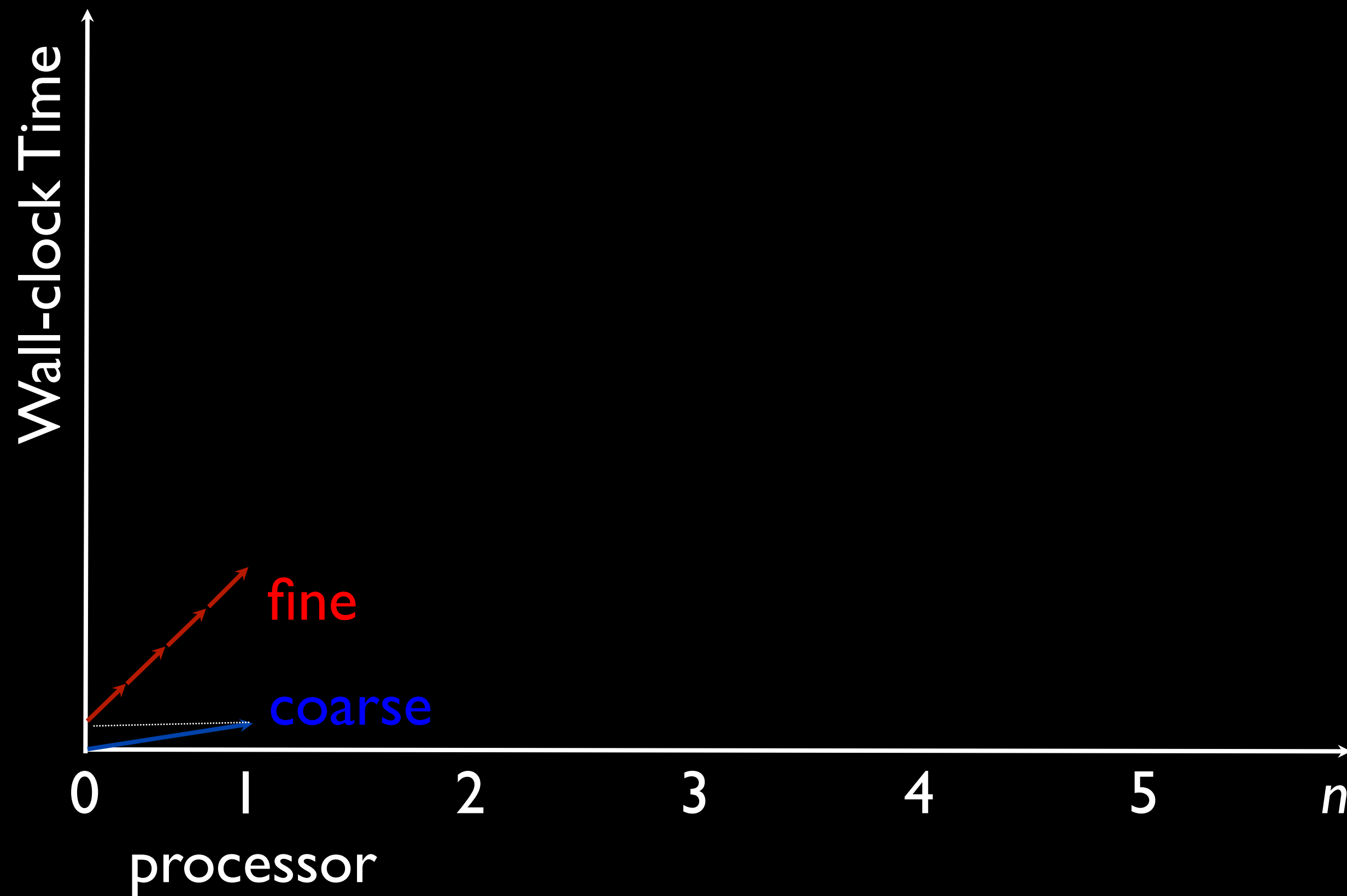
Parareal simulation for Lattice Boltzmann Equation

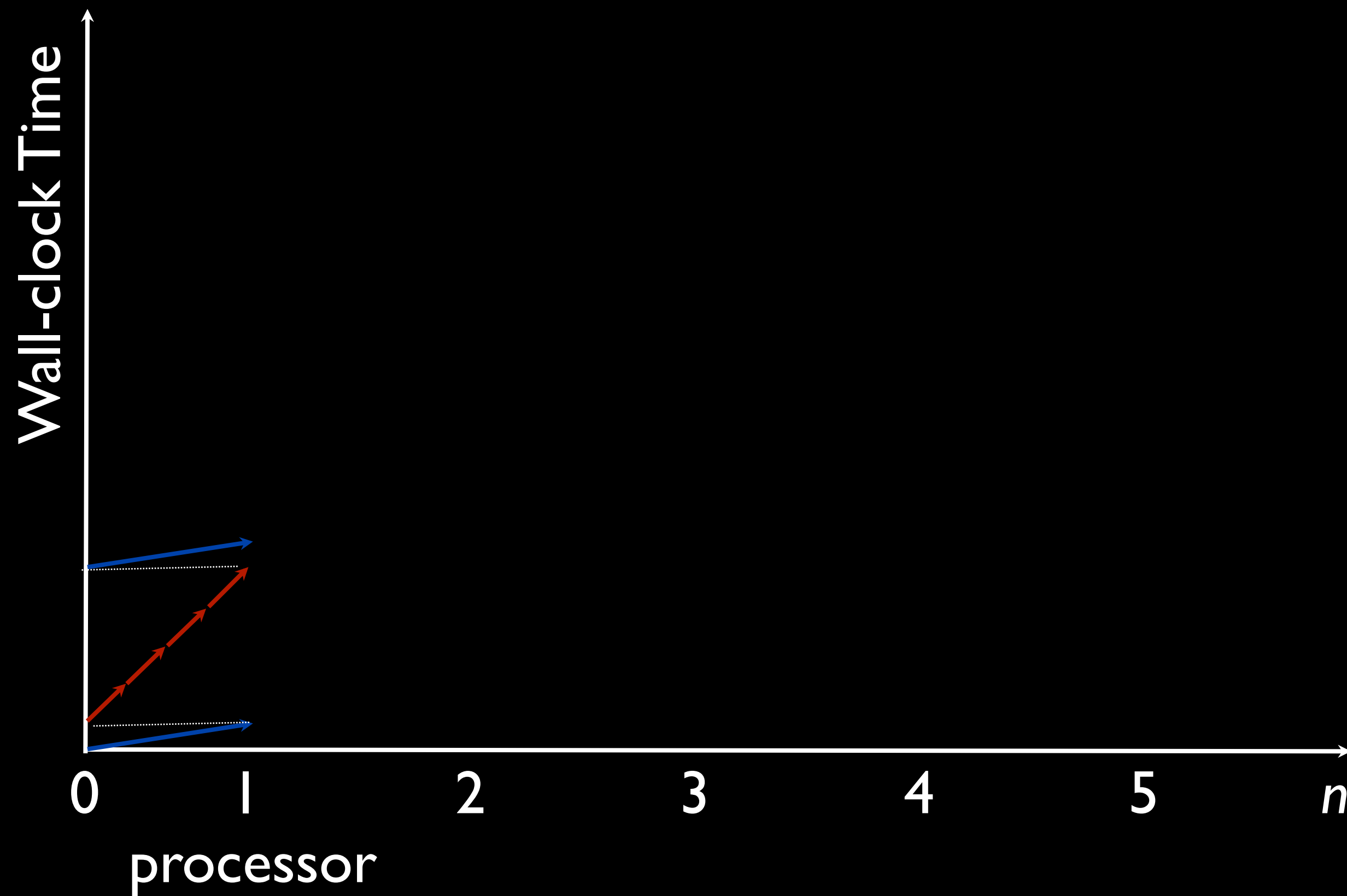


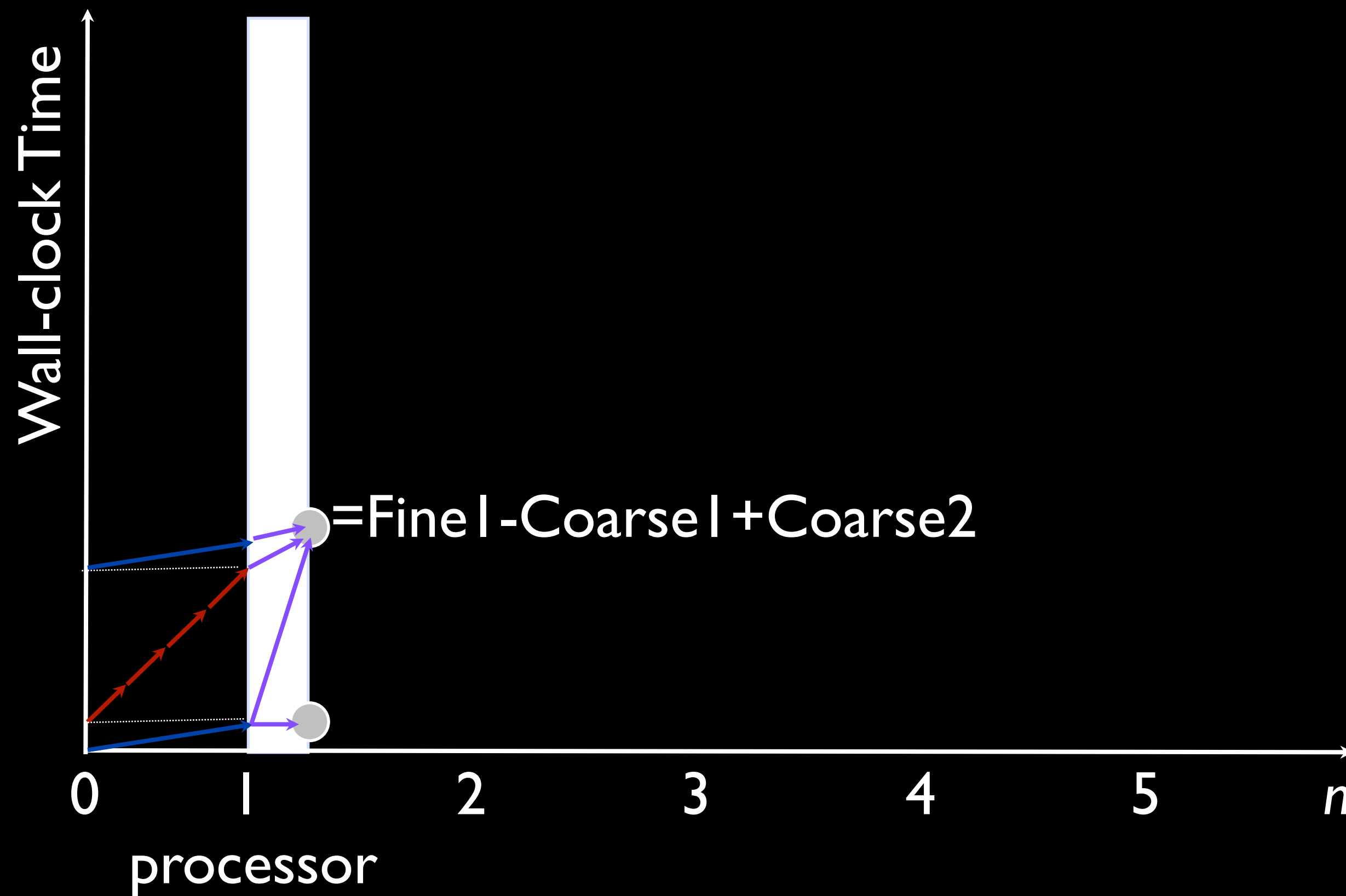
Grid Refinement

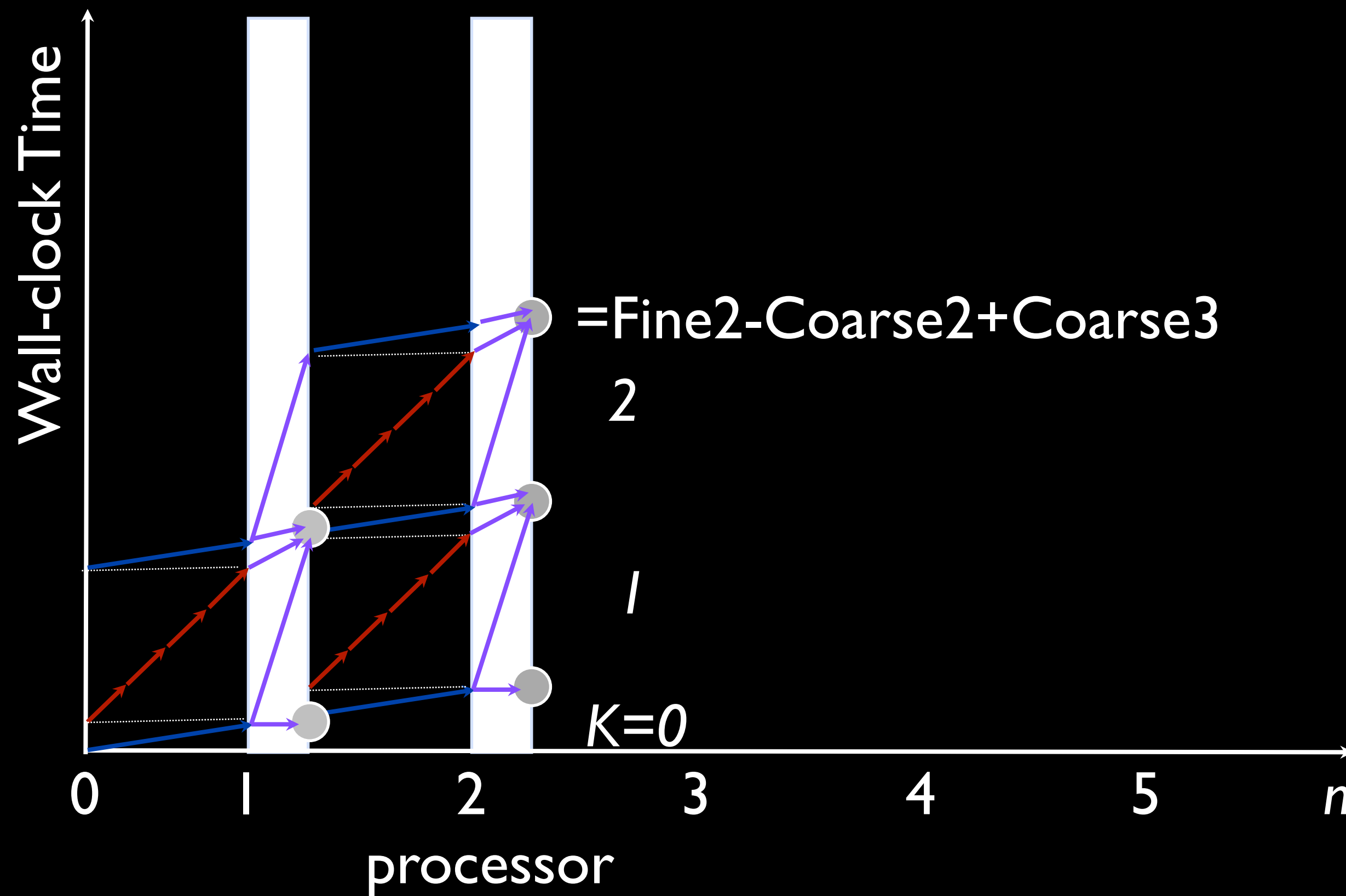
- Address stability and accuracy concerns
- Coarsening and extrapolating schemes
- Careful coupling between fine and coarse solver

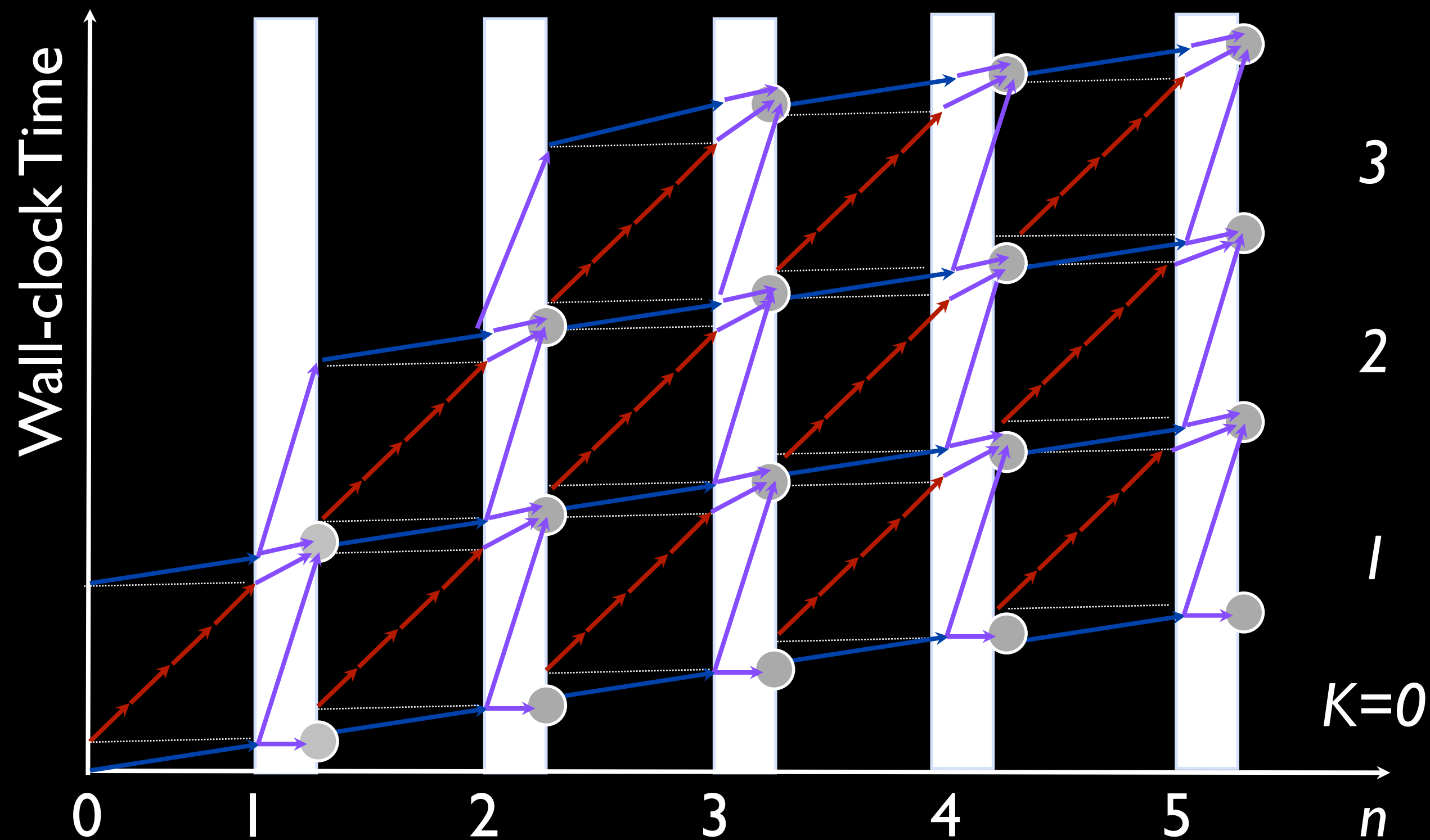




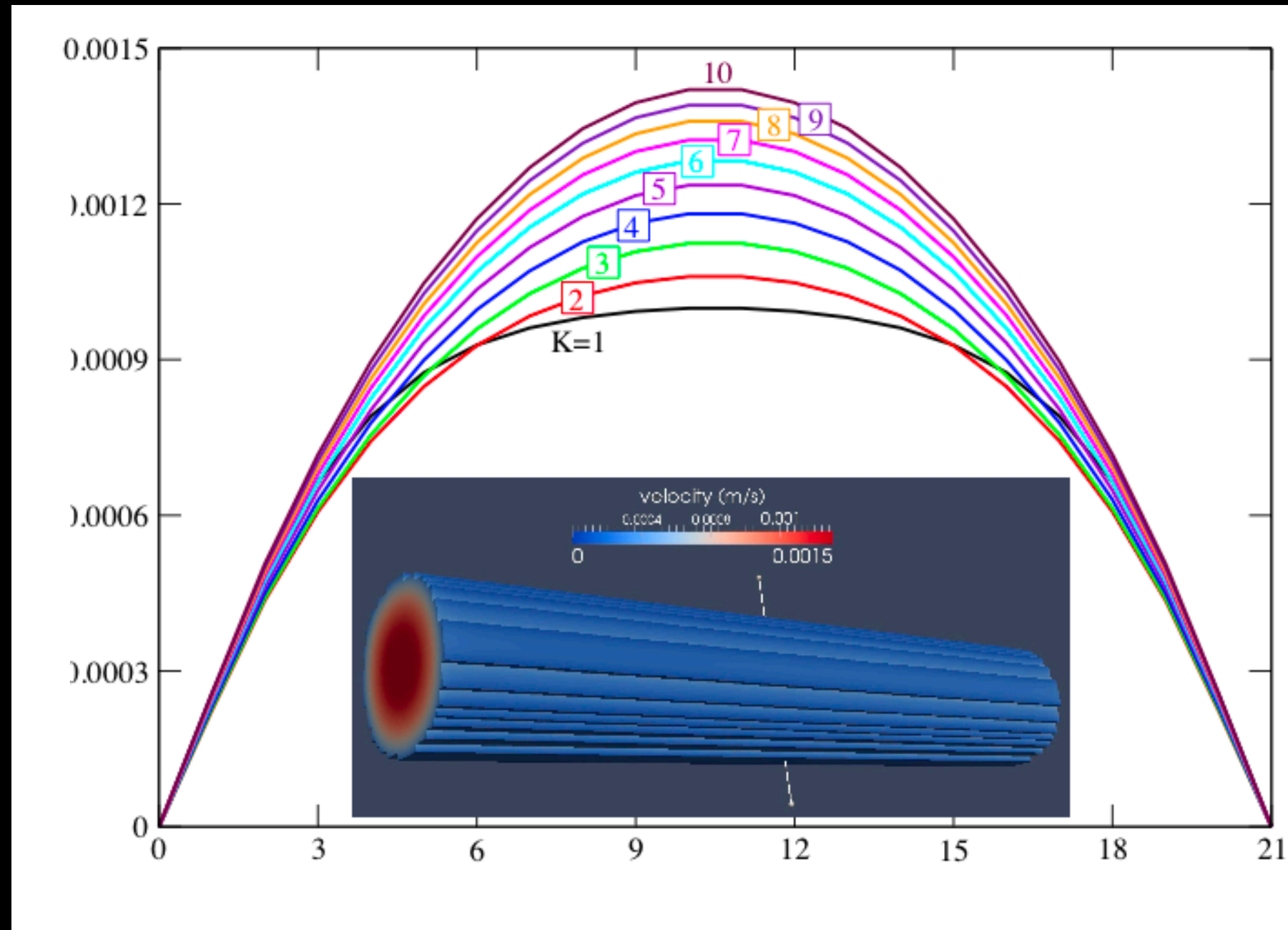
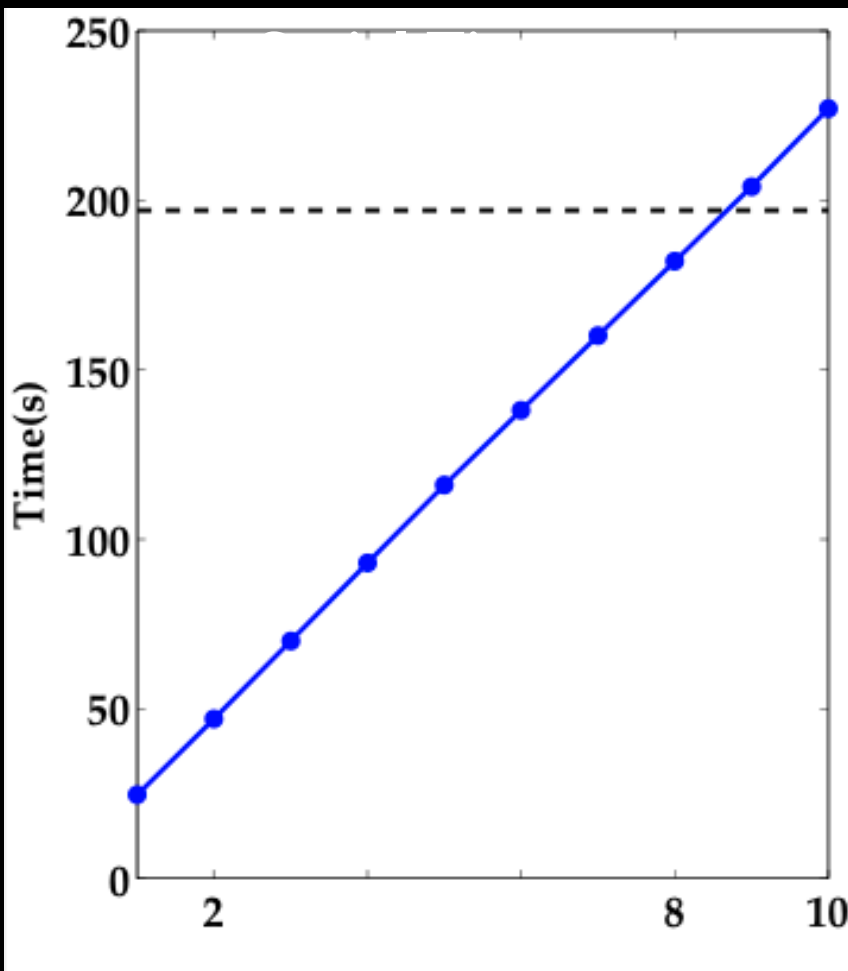




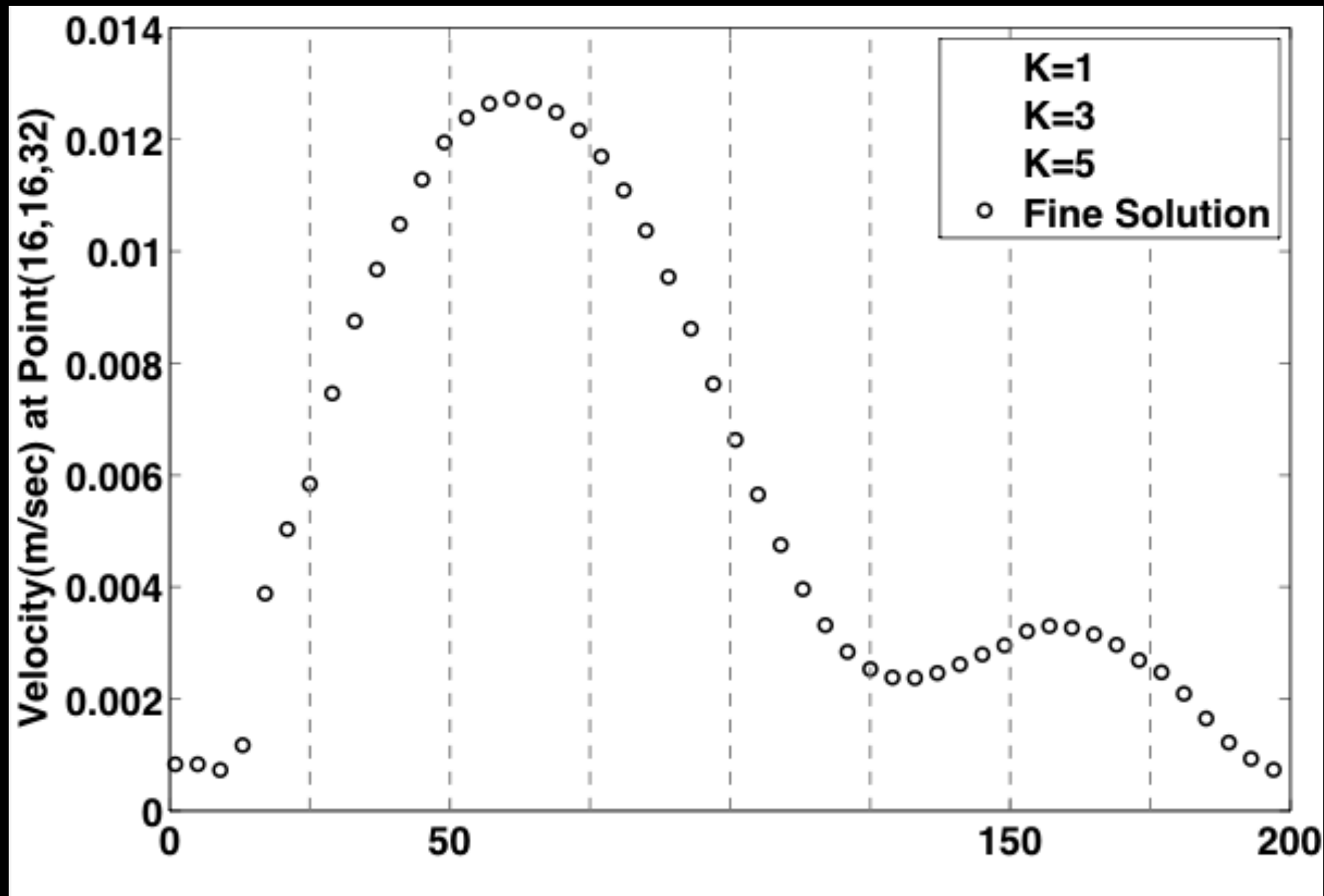




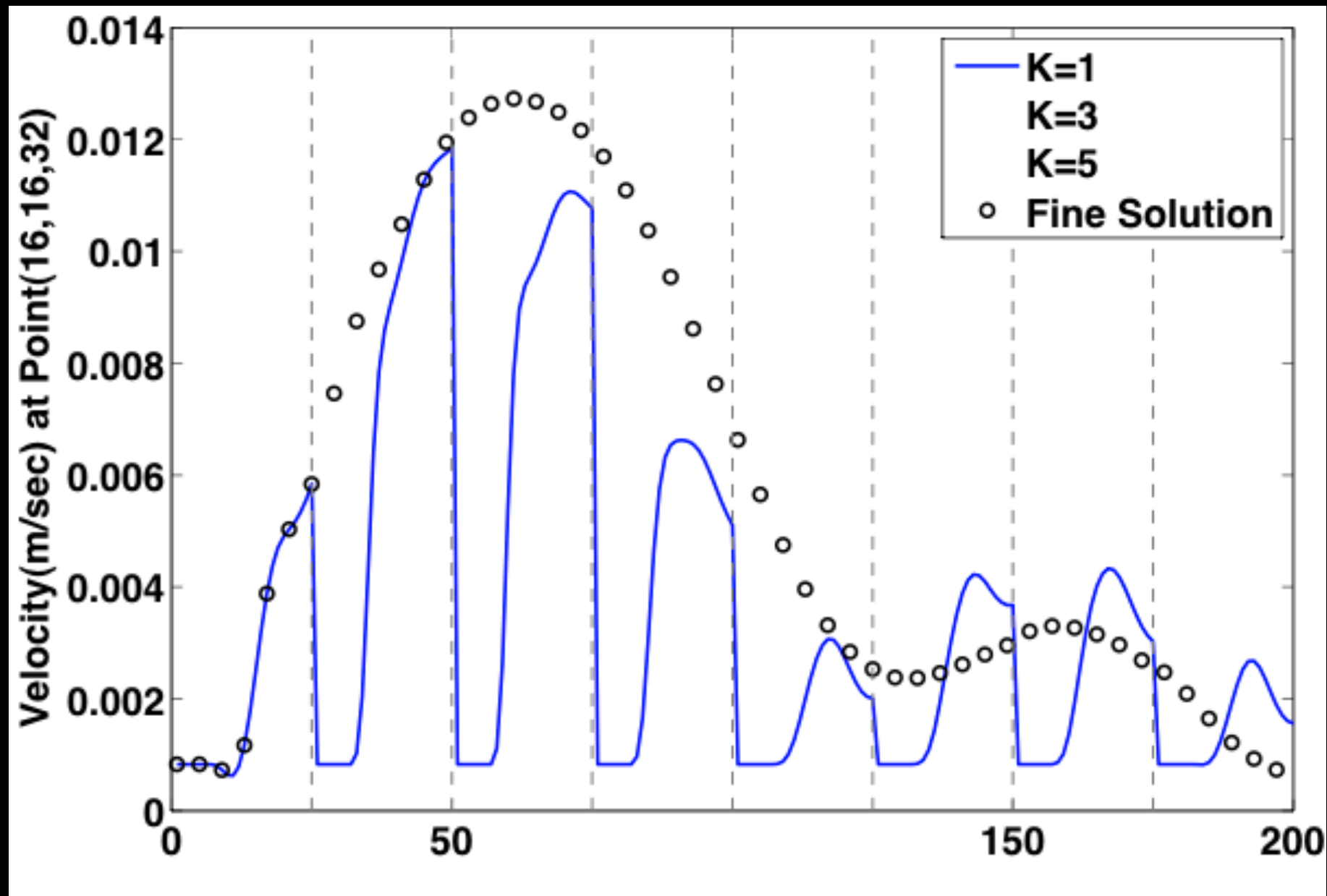
Runtime vs. Accuracy



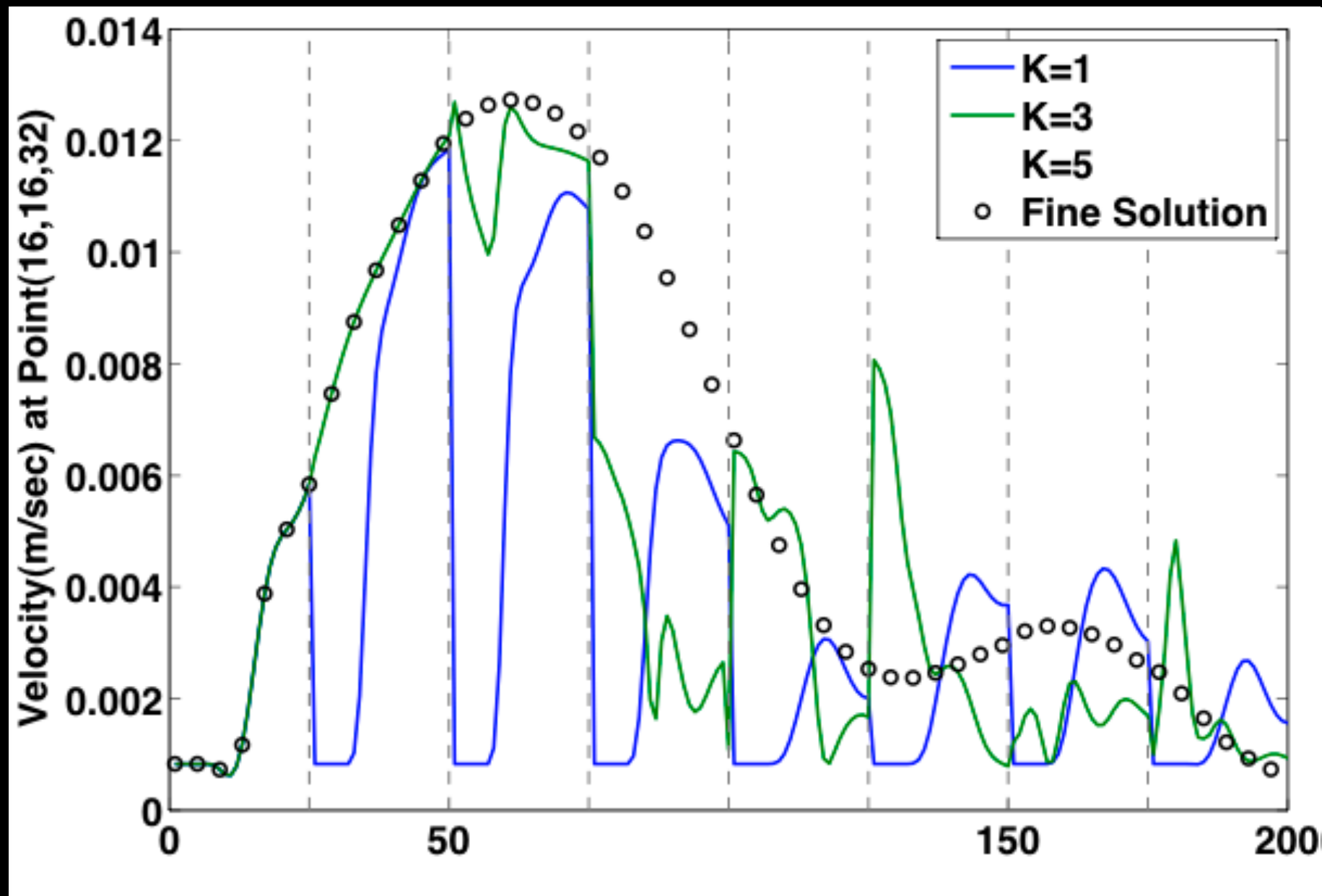
Time Dependent Phenomena



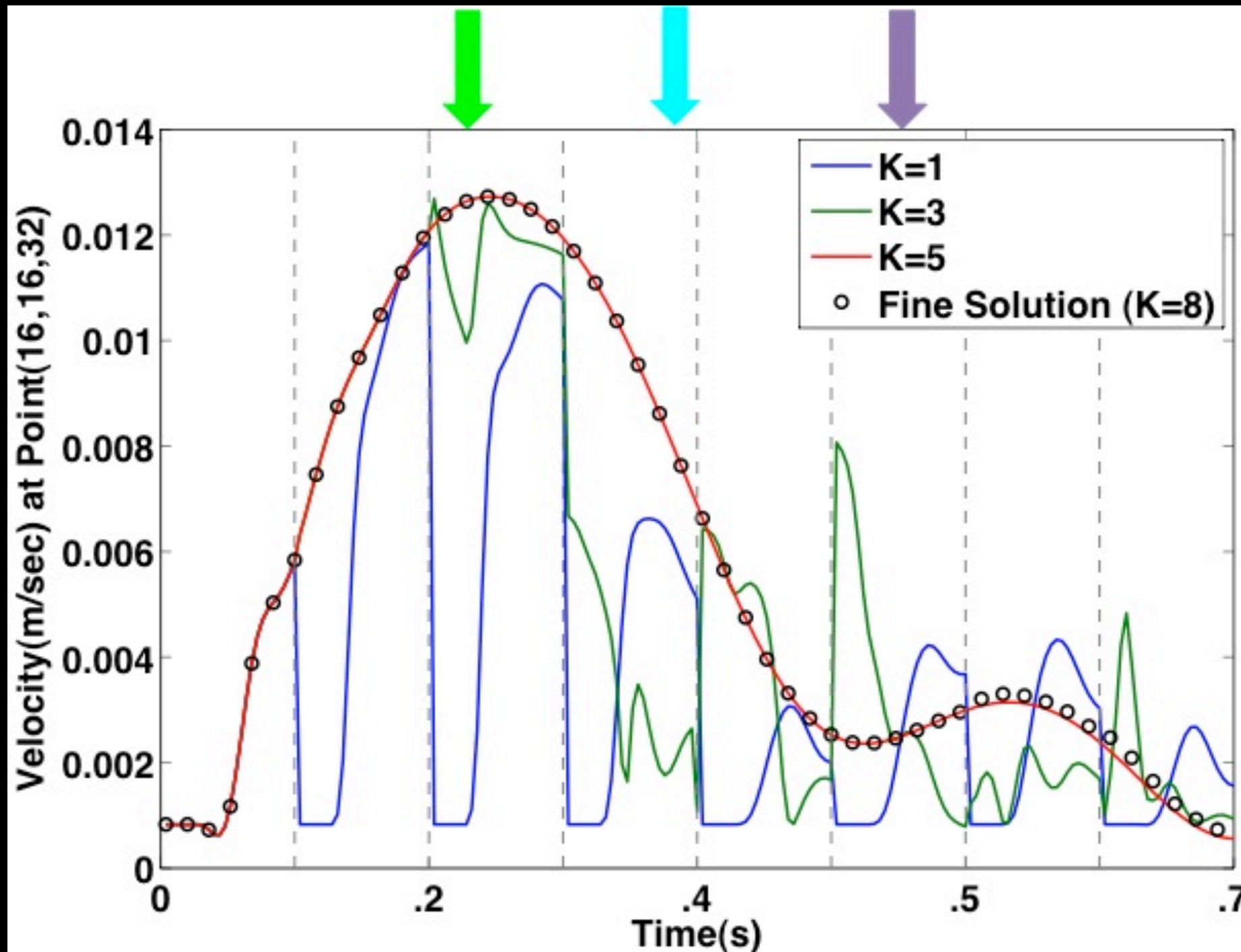
Time Dependent Phenomena



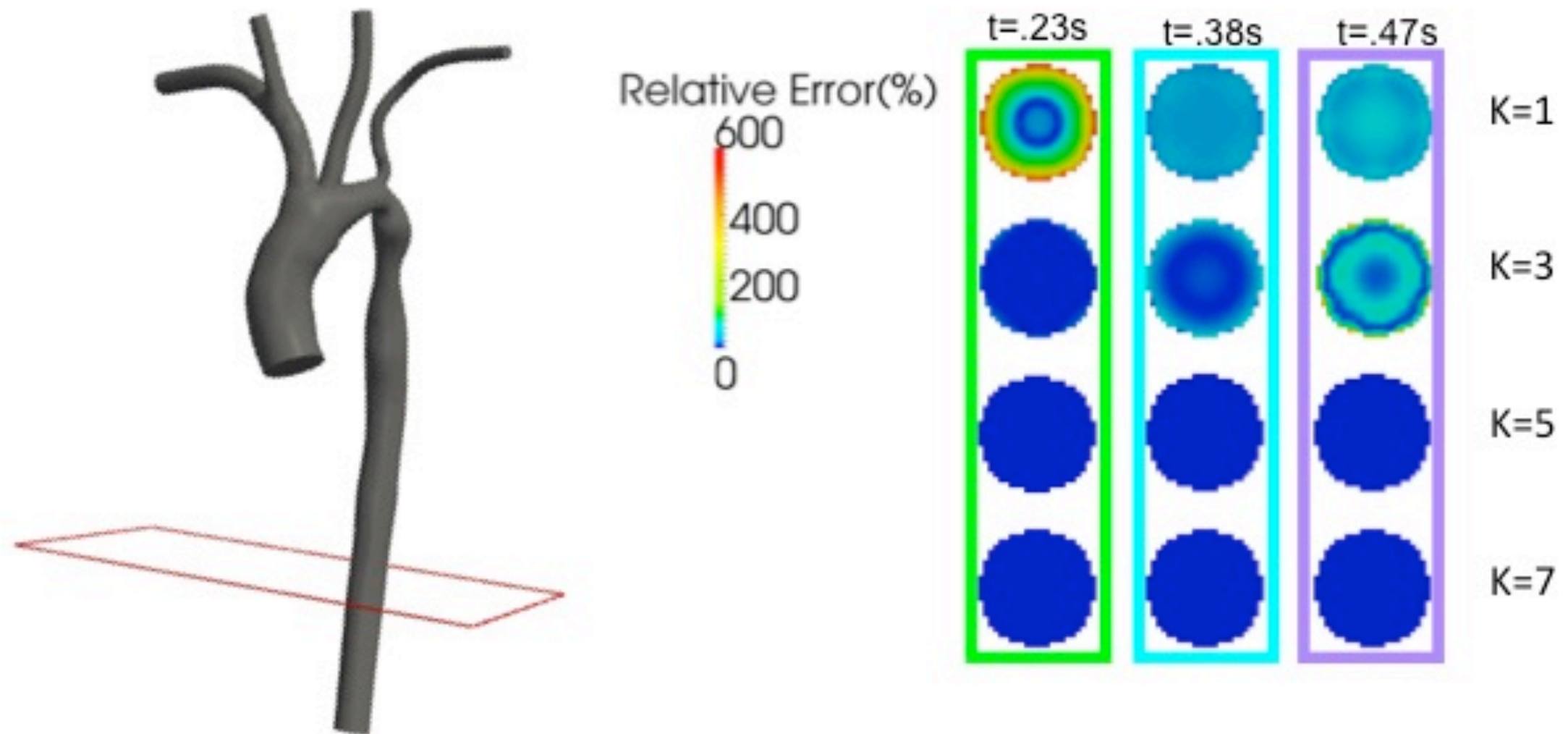
Time Dependent Phenomena



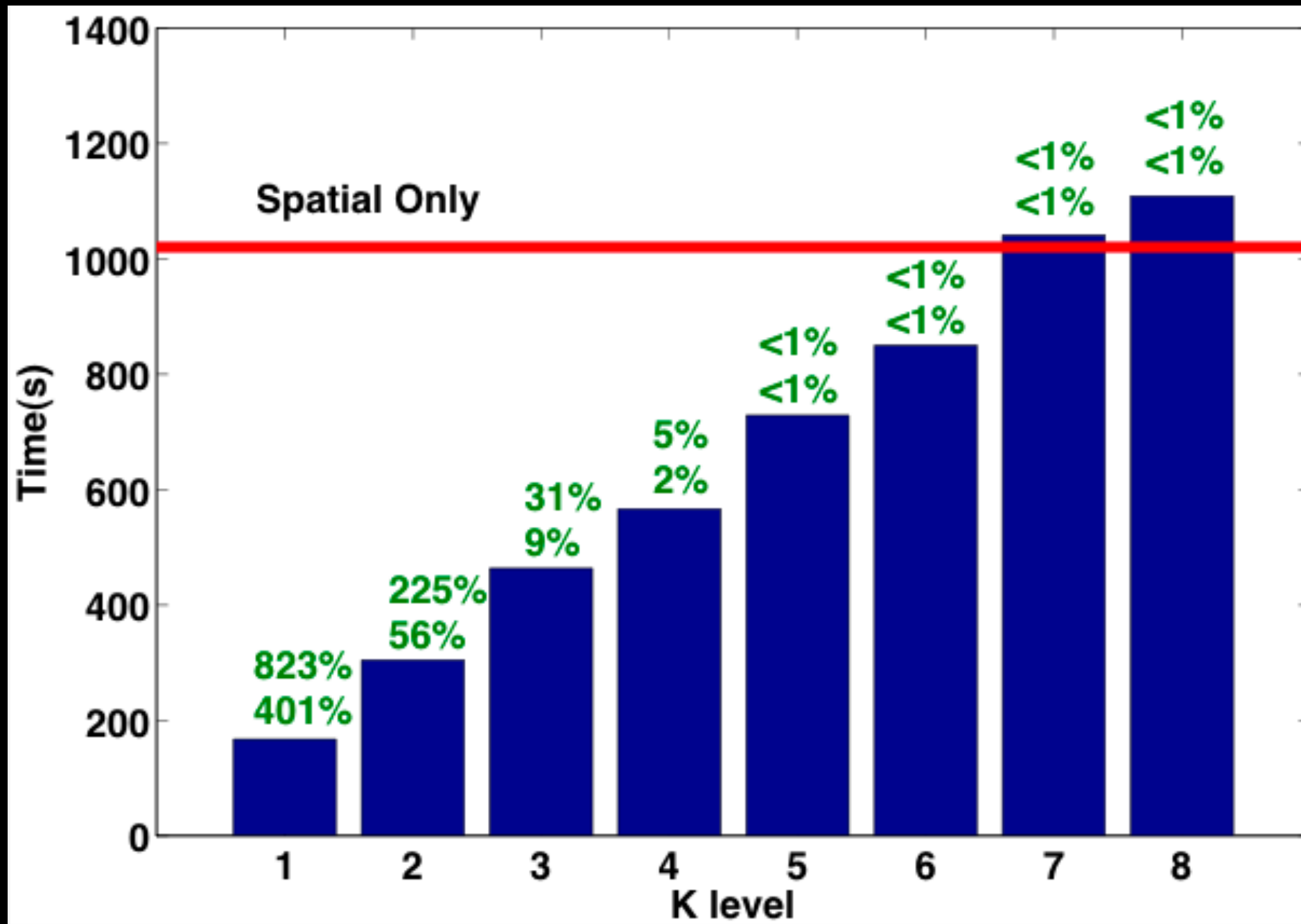
Time Dependent Phenomena



Relative Error



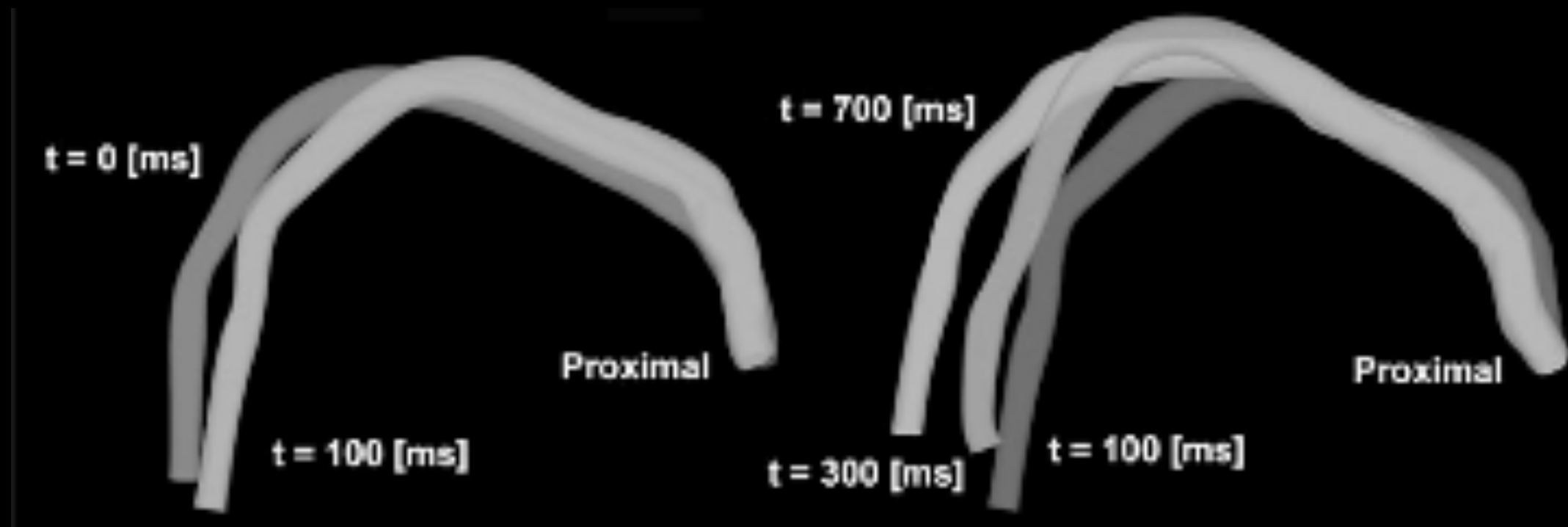
Time-to-Solution



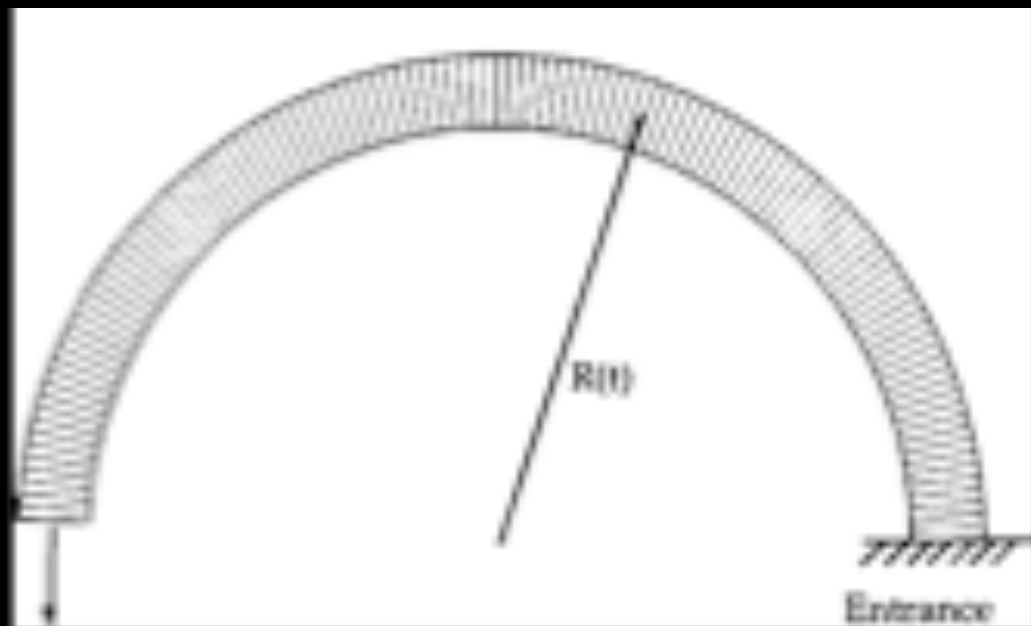
Peters Randles, et al. Supercomputing, 2013 (submitted)

32,768 Cores of the IBM Blue Gene/P

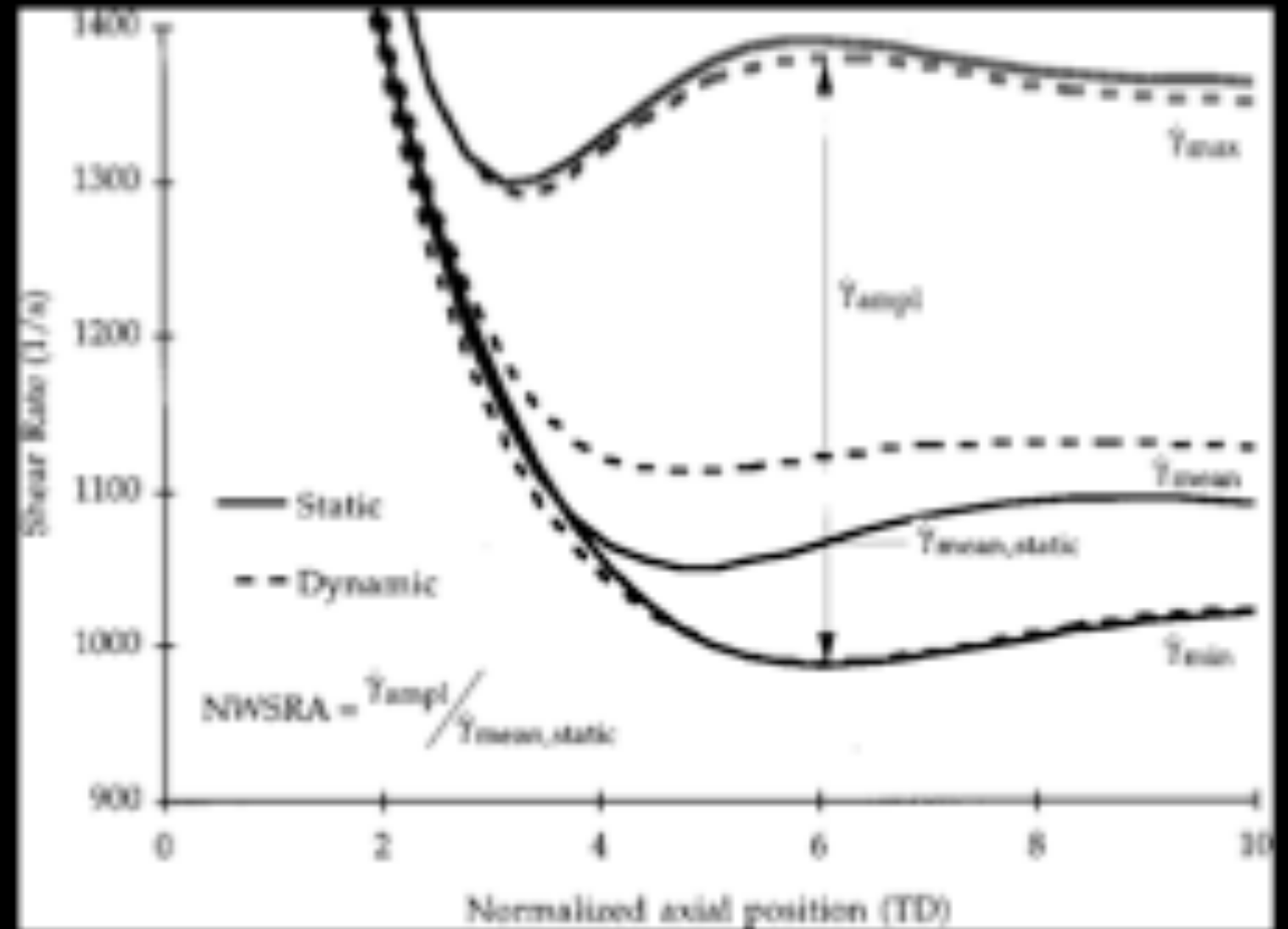
Curvature Change Over One Heartbeat



Wall Shear Rate Impact

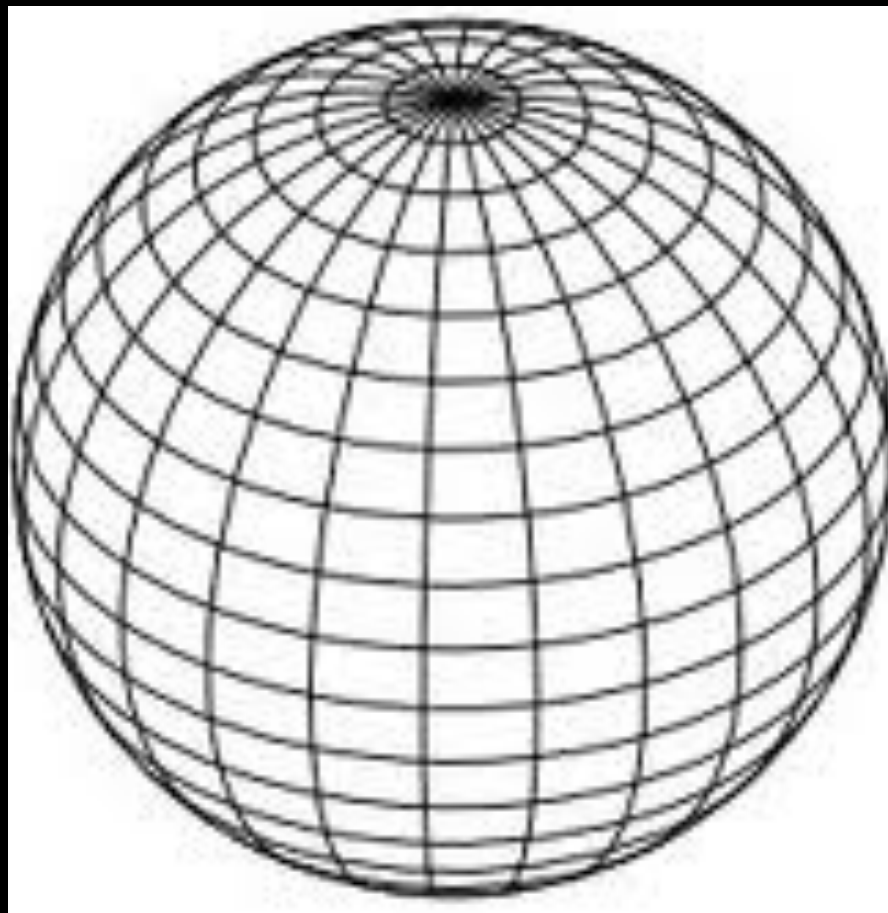


Wall Shear Rate varied as much as 52%



Santamarina et al. Annals of Biomedical Engineering, 1998

Fluid modeling on a moving mesh



- General relativity formulation
- Bernstein model for the expanding universe
- Lattice Boltzmann implementation

Force Term

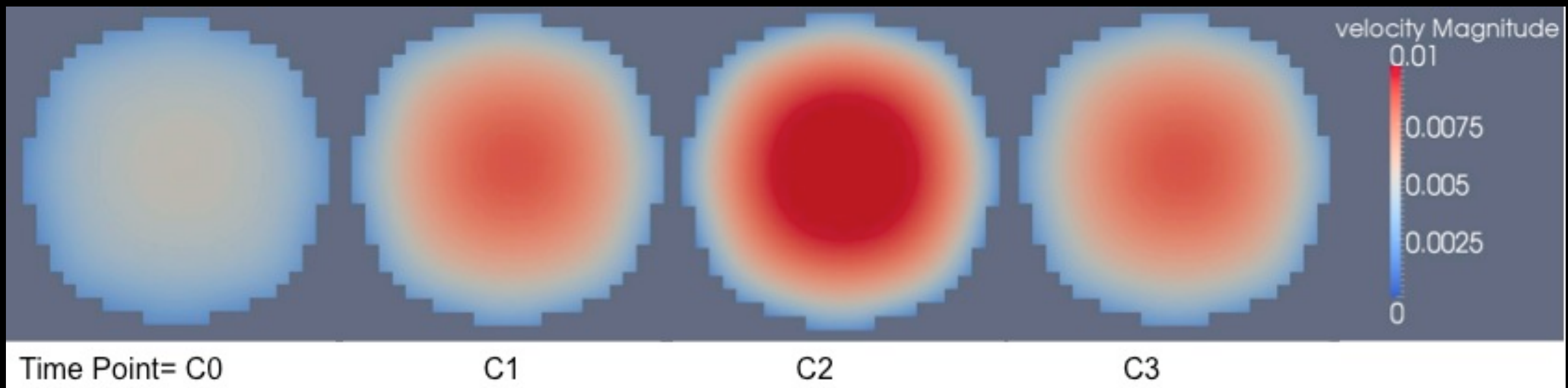
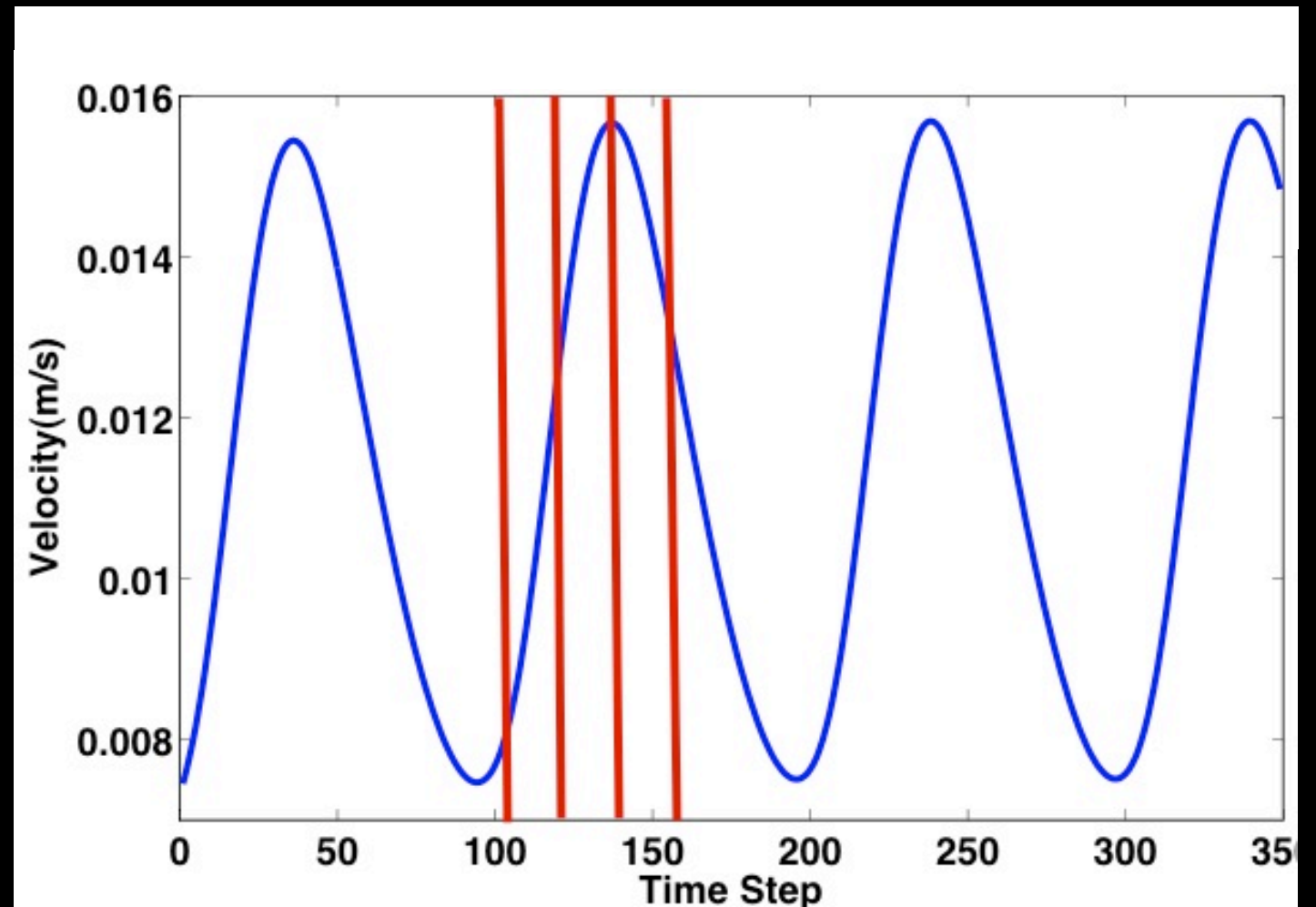
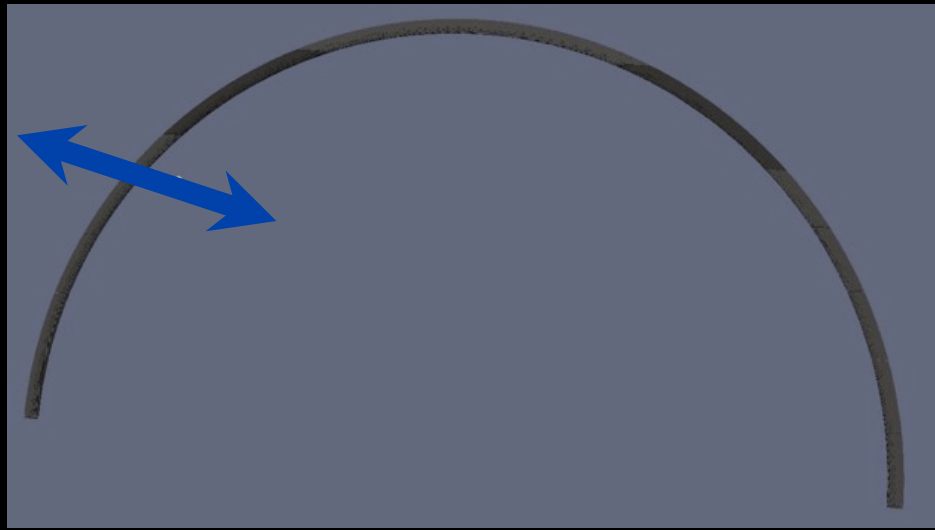
$$f_i(\vec{x} + \vec{c}_i \Delta t, t + \Delta t) = f_i(\vec{x}, t) - \omega \Delta t (f_i - f_i^{eq})(\vec{x}, t) + \vec{g} \cdot \partial v f$$

Deformational Force in Continuum Space:

$$\vec{g} = -\frac{\dot{R}}{R} \vec{v}$$

External
Force

Sinusoidal Expansion

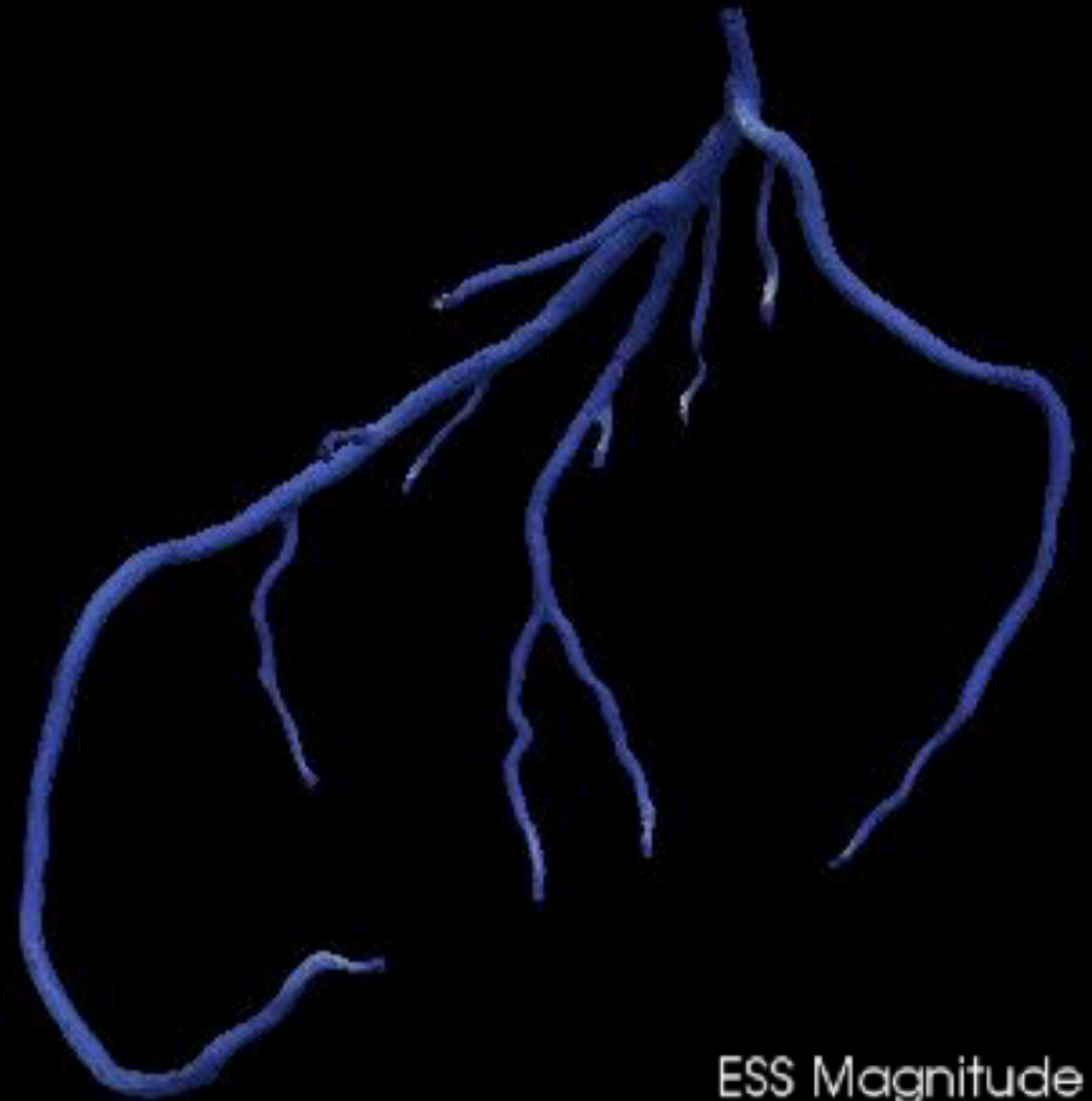




Static



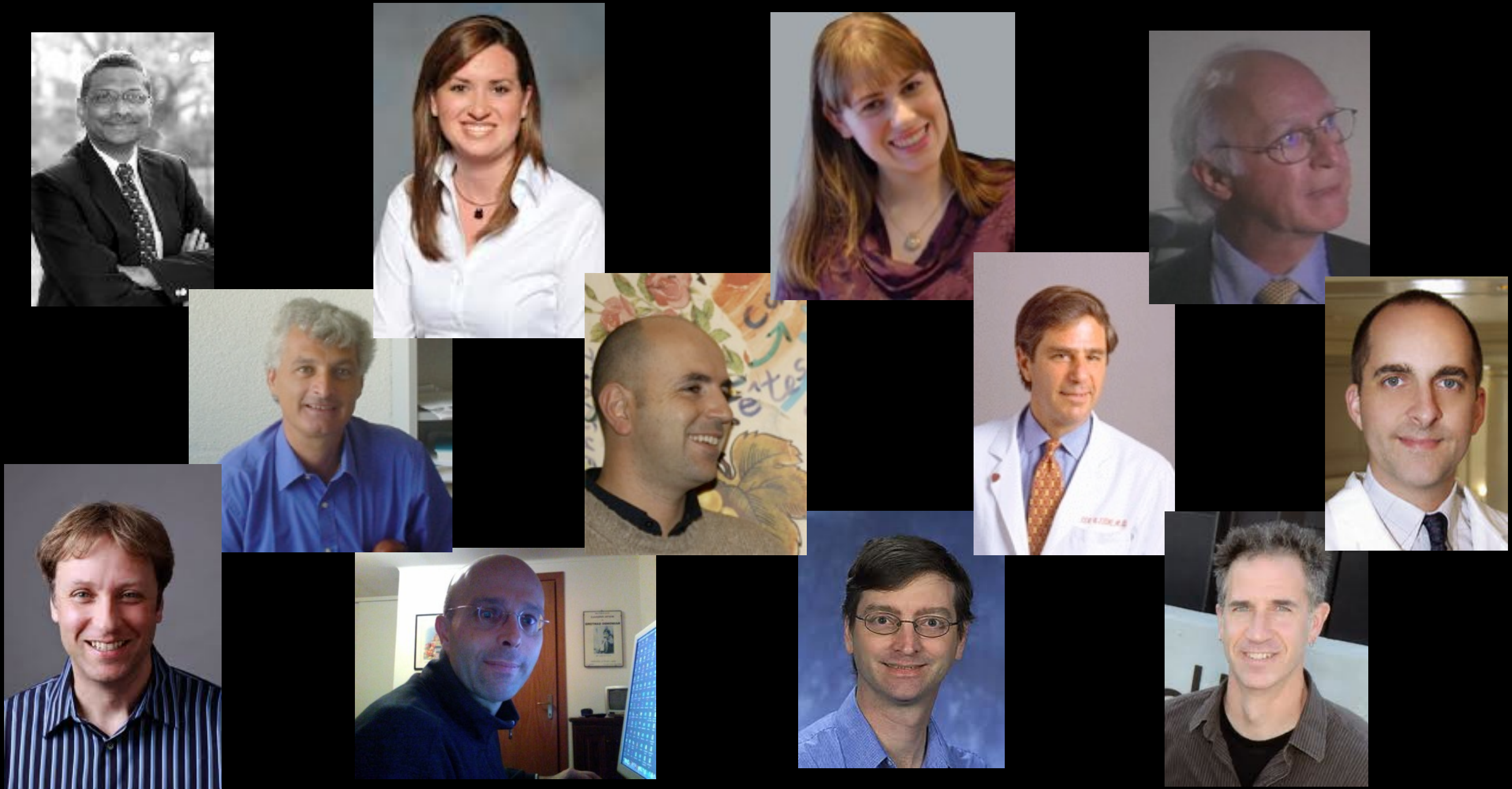
With deformational force



ESS Magnitude



Multiscale Hemodynamics Team



Massimo Bernaschi - Michelle Borkin - Mauro Bisson - Ahmet Coskun - Charles Feldman - Bill Gropp - Jeff Hammond - Joseph Insley - Vivek Kale - Efthimios Kaxiras - Jonas Latt - Simone Melchionna - Dimitris Mitsouras - Amanda Peters Randles- Hanspeter Pfister - Frank Rybicki - Joy Sircar - Michael Steigner - Peter Stone - Sauro Succi - Frederick Welt